

Vectors: Dot Products & Projections

Calculus II

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TTU

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Dot Product (Definition)

Definition

Dot Product in \mathbb{R}^2 :

The **dot product** of vectors $\vec{v} = \langle v_1, v_2 \rangle$ and $\vec{w} = \langle w_1, w_2 \rangle$ is defined by:

$$\mathbf{v} \cdot \mathbf{w} := v_1 w_1 + v_2 w_2$$

Definition

Dot Product in \mathbb{R}^3 :

The **dot product** of vectors $\vec{v} = \langle v_1, v_2, v_3 \rangle$ and $\vec{w} = \langle w_1, w_2, w_3 \rangle$ is defined by:

$$\mathbf{v} \cdot \mathbf{w} := v_1 w_1 + v_2 w_2 + v_3 w_3$$

REMARKS:

- Notice that the dot product $\mathbf{v} \cdot \mathbf{w}$ is a **scalar**.
- Going forward, the focus will be on **3-D vectors** (e.g. $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$)

Dot Product (Properties)

Let vectors $\mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbb{R}^3$ and scalar $c \in \mathbb{R}$. Then:

- $\mathbf{v} \cdot \mathbf{v} = \|\mathbf{v}\|^2$
- $\vec{\mathbf{0}} \cdot \mathbf{v} = \mathbf{v} \cdot \vec{\mathbf{0}} = 0$
- $\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v}$
- $c(\mathbf{v} \cdot \mathbf{w}) = (c\mathbf{v}) \cdot \mathbf{w} = \mathbf{v} \cdot (c\mathbf{w})$
- $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$

Dot Product (Properties)

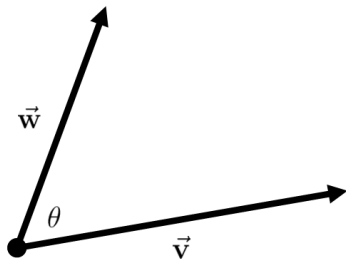
Let vectors $\mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbb{R}^3$ and scalar $c \in \mathbb{R}$. Then:

- $\mathbf{v} \cdot \mathbf{v} = \|\mathbf{v}\|^2$
- $\vec{0} \cdot \mathbf{v} = \mathbf{v} \cdot \vec{0} = 0$
- $\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v}$
- $c(\mathbf{v} \cdot \mathbf{w}) = (c\mathbf{v}) \cdot \mathbf{w} = \mathbf{v} \cdot (c\mathbf{w})$
- $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$

PROOF: Let $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$. Then:

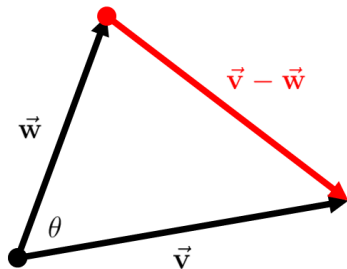
$$\mathbf{v} \cdot \mathbf{v} = \langle v_1, v_2, v_3 \rangle \cdot \langle v_1, v_2, v_3 \rangle = v_1^2 + v_2^2 + v_3^2 = \left(\sqrt{v_1^2 + v_2^2 + v_3^2} \right)^2 = \|\mathbf{v}\|^2 \quad \text{QED}$$

Dot Product (Geometric Formula Derivation)



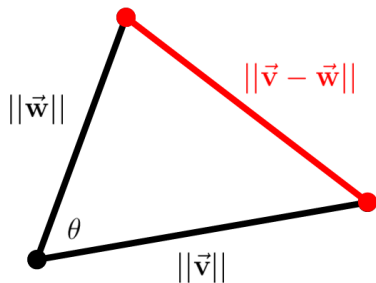
- Given vectors $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$ and $\mathbf{w} = \langle w_1, w_2, w_3 \rangle$.

Dot Product (Geometric Formula Derivation)



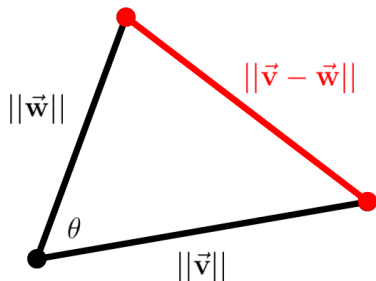
- Form vector $\mathbf{v} - \mathbf{w} = \langle v_1 - w_1, v_2 - w_2, v_3 - w_3 \rangle$.

Dot Product (Geometric Formula Derivation)



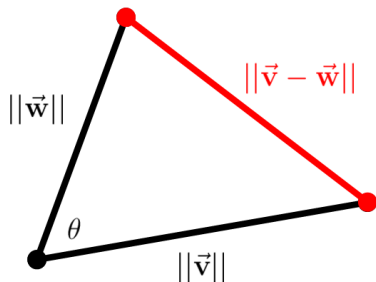
- Take norms of all three vectors and consider the resulting **triangle**.

Dot Product (Geometric Formula Derivation)



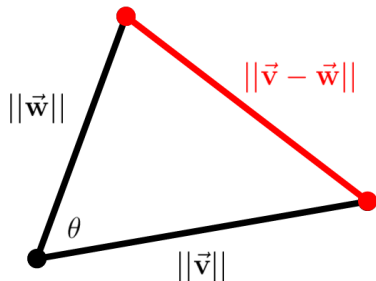
Trig Review: What result relates all three norms and the angle θ ??

Dot Product (Geometric Formula Derivation)



Law of Cosines: $\|\mathbf{v} - \mathbf{w}\|^2 = \|\mathbf{v}\|^2 + \|\mathbf{w}\|^2 - 2\|\mathbf{v}\|\|\mathbf{w}\|\cos\theta$

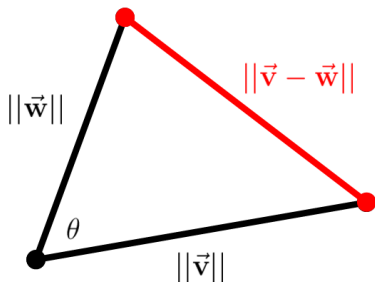
Dot Product (Geometric Formula Derivation)



Solve for the cosine term:

$$\cos \theta = \frac{\|\vec{v}\|^2 + \|\vec{w}\|^2 - \|\vec{v} - \vec{w}\|^2}{2\|\vec{v}\|\|\vec{w}\|}$$

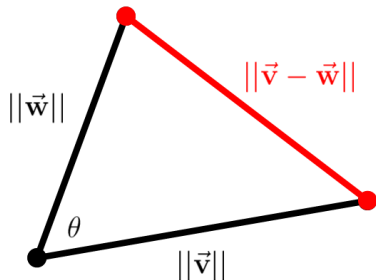
Dot Product (Geometric Formula Derivation)



Write all norms in the numerator in terms of vector components:

$$\cos \theta = \frac{v_1^2 + v_2^2 + v_3^2 + w_1^2 + w_2^2 + w_3^2 - [(v_1 - w_1)^2 + (v_2 - w_2)^2 + (v_3 - w_3)^2]}{2\|\mathbf{v}\|\|\mathbf{w}\|}$$

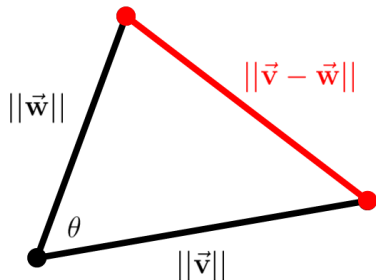
Dot Product (Geometric Formula Derivation)



Simplify numerator:

$$\cos \theta = \frac{2v_1w_1 + 2v_2w_2 + 2v_3w_3}{2\|\mathbf{v}\|\|\mathbf{w}\|}$$

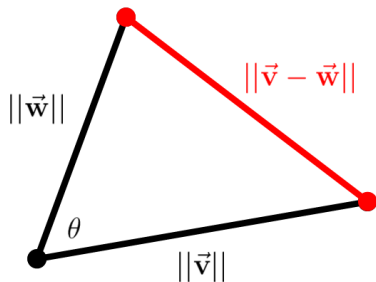
Dot Product (Geometric Formula Derivation)



Simplify fraction:

$$\cos \theta = \frac{v_1 w_1 + v_2 w_2 + v_3 w_3}{\|\mathbf{v}\| \|\mathbf{w}\|}$$

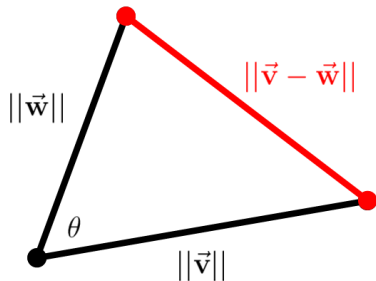
Dot Product (Geometric Formula Derivation)



Realize that the numerator is a dot product:

$$\cos \theta = \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|}$$

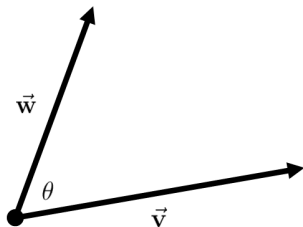
Dot Product (Geometric Formula Derivation)



Solve for the dot product:

$$\mathbf{v} \cdot \mathbf{w} = \|\mathbf{v}\| \|\mathbf{w}\| \cos \theta$$

Dot Product (Coordinate-Free Definition)



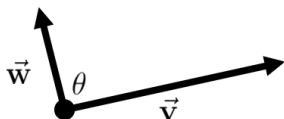
Definition

Let θ be the smallest positive angle between vectors $\mathbf{v}, \mathbf{w} \in \mathbb{R}^3$. Then:

$$\mathbf{v} \cdot \mathbf{w} = \|\mathbf{v}\| \|\mathbf{w}\| \cos \theta \quad \text{where } \theta \in [0, \pi]$$

- Alternative notation for the angle between vectors $\mathbf{v}, \mathbf{w} : \theta_{vw}$

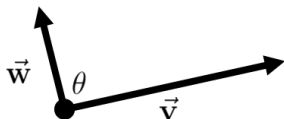
Dot Product (Orthogonality)



Theorem

Vectors $\mathbf{v}, \mathbf{w} \in \mathbb{R}^3$ are **orthogonal** $\iff \mathbf{v} \perp \mathbf{w} \iff \mathbf{v} \cdot \mathbf{w} = 0$

Dot Product (Orthogonality)



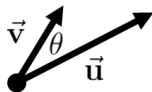
Theorem

Vectors $\mathbf{v}, \mathbf{w} \in \mathbb{R}^3$ are **orthogonal** $\iff \mathbf{v} \perp \mathbf{w} \iff \mathbf{v} \cdot \mathbf{w} = 0$

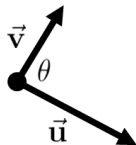
PROOF:

\mathbf{v}, \mathbf{w} are **orthogonal** $\iff \theta = \pi/2 \iff \mathbf{v} \cdot \mathbf{w} = \|\mathbf{v}\| \|\mathbf{w}\| \cos(\pi/2) = 0$ QED

Dot Product (Geometric Interpretation)



θ is acute
 $\vec{u} \cdot \vec{v} > 0$

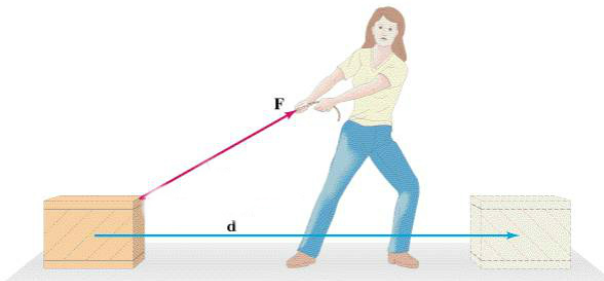


θ is 90°
 $\vec{u} \cdot \vec{v} = 0$



θ is obtuse
 $\vec{u} \cdot \vec{v} < 0$

Dot Product (Work)



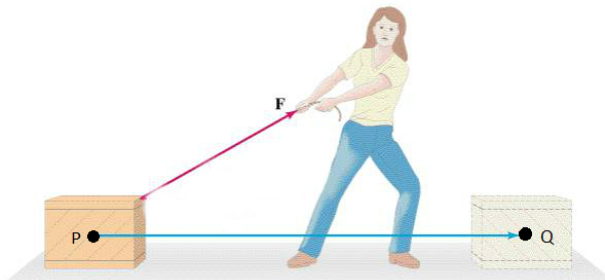
Definition

The **work**, W , done by a constant force $\vec{\mathbf{F}}$ on an object displacing it by $\vec{\mathbf{d}}$ is:

$$W := \vec{\mathbf{F}} \cdot \vec{\mathbf{d}}$$

PROOF: Take Physics (Mechanics)

Dot Product (Work)



Definition

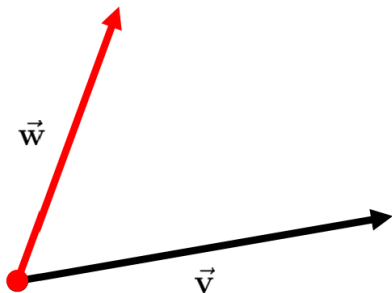
The **work**, W , done by a constant force \vec{F} on an object moving it from P to Q is:

$$W := \vec{F} \cdot \vec{PQ}$$

PROOF: Take Physics (Mechanics)

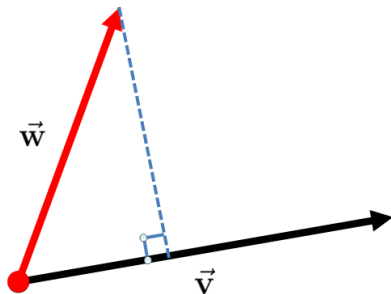
Projection (Example 1)

Project w onto v .



Projection (Example 1)

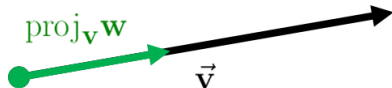
Project \mathbf{w} onto \mathbf{v} .



Drop perpendicular line from \mathbf{w} to \mathbf{v} .

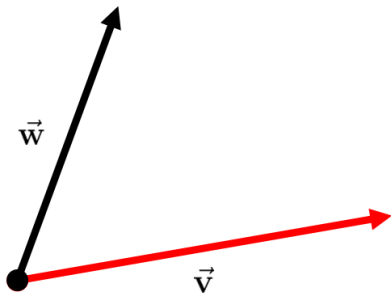
Projection (Example 1)

Project w onto v .



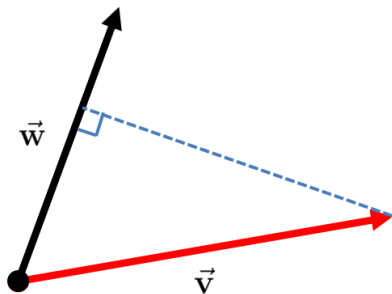
Projection (Example 2)

Project \mathbf{v} onto \mathbf{w} .



Projection (Example 2)

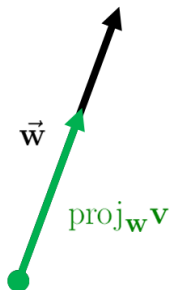
Project \mathbf{v} onto \mathbf{w} .



Drop perpendicular line from \mathbf{v} to \mathbf{w} .

Projection (Example 2)

Project \mathbf{v} onto \mathbf{w} .



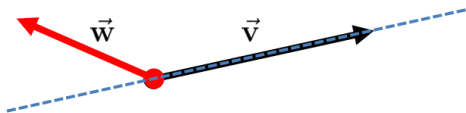
Projection (Example 3)

Project w onto v .



Projection (Example 3)

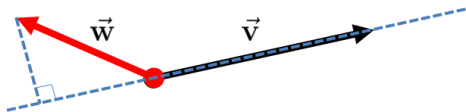
Project \mathbf{w} onto \mathbf{v} .



Draw line extension through \mathbf{v} .

Projection (Example 3)

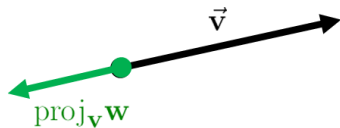
Project \mathbf{w} onto \mathbf{v} .



Drop perpendicular line from \mathbf{w} to line extension.

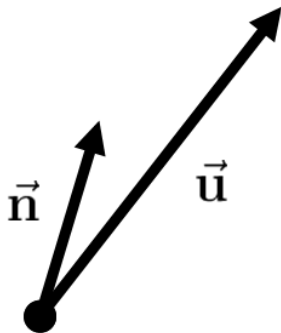
Projection (Example 3)

Project w onto v .



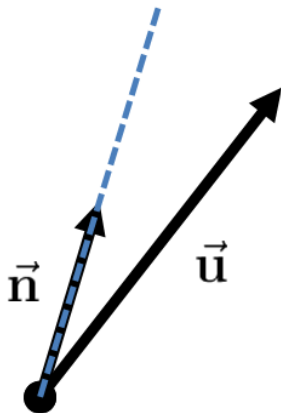
Projection (Example 4)

Project \mathbf{u} onto \mathbf{n} .



Projection (Example 4)

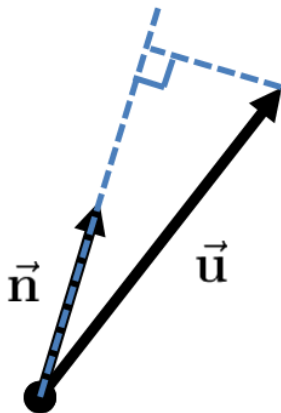
Project \mathbf{u} onto \mathbf{n} .



Draw line extension through \mathbf{n} .

Projection (Example 4)

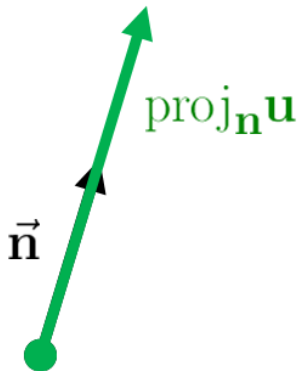
Project \mathbf{u} onto \mathbf{n} .



Drop perpendicular line from \mathbf{u} to line extension.

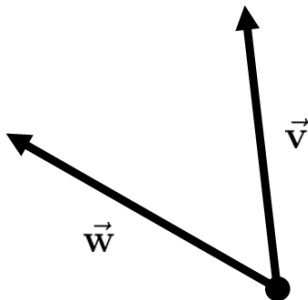
Projection (Example 4)

Project \mathbf{u} onto \mathbf{n} .



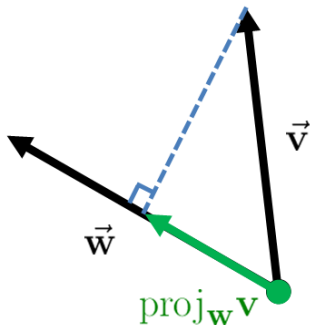
Projection (Formula Derivation)

Determine a formula for $\text{proj}_{\vec{w}} \vec{v}$, the **projection** of vector \vec{v} onto vector \vec{w} .



Projection (Formula Derivation)

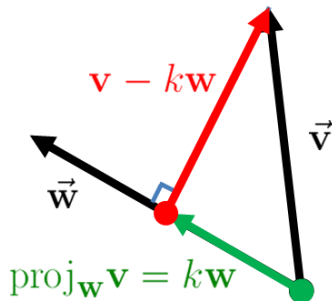
Determine a formula for $\text{proj}_{\vec{w}}\vec{v}$, the **projection** of vector \vec{v} onto vector \vec{w} .



Notice that $(\text{proj}_{\vec{w}}\vec{v}) \parallel \vec{w} \implies \text{proj}_{\vec{w}}\vec{v} = k\vec{w}$, where $k \in \mathbb{R}$.

Projection (Formula Derivation)

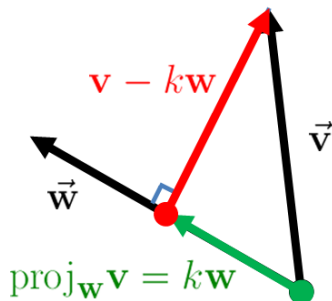
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



Form vector $\vec{v} - k\vec{w}$.

Projection (Formula Derivation)

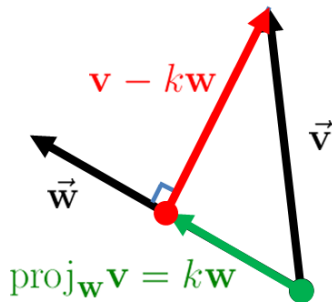
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



Notice that $(\mathbf{v} - k\mathbf{w}) \perp \mathbf{w}$.

Projection (Formula Derivation)

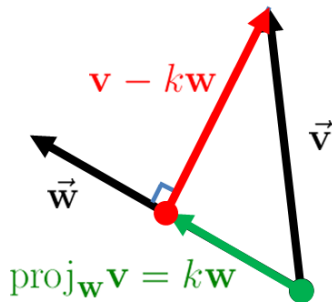
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies (\mathbf{v} - k\mathbf{w}) \cdot \mathbf{w} = 0$$

Projection (Formula Derivation)

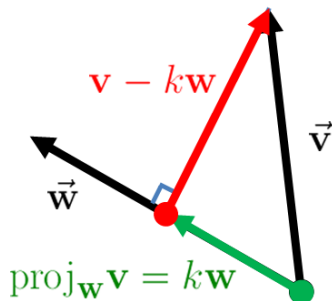
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies \mathbf{v} \cdot \mathbf{w} - (k\mathbf{w}) \cdot \mathbf{w} = 0$$

Projection (Formula Derivation)

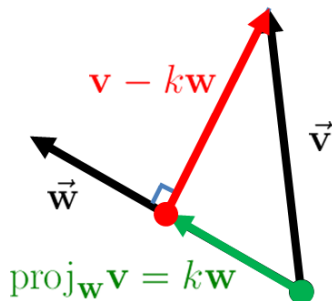
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies \mathbf{v} \cdot \mathbf{w} - k(\mathbf{w} \cdot \mathbf{w}) = 0$$

Projection (Formula Derivation)

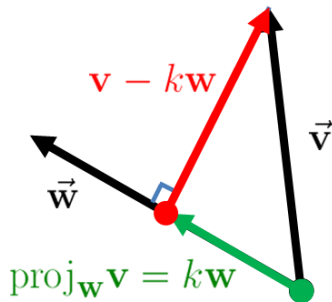
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies \mathbf{v} \cdot \mathbf{w} = k(\mathbf{w} \cdot \mathbf{w})$$

Projection (Formula Derivation)

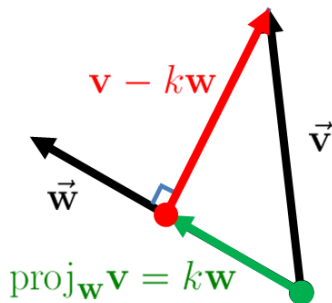
Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies k = \frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}$$

Projection (Formula Derivation)

Determine value of scalar k in terms of given vectors \mathbf{v} & \mathbf{w} .



$$\implies k = \frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}$$

$$\implies \text{proj}_{\mathbf{w}} \mathbf{v} = k\mathbf{w} = \left(\frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}} \right) \mathbf{w}$$

Projection (Formula)

Definition

The **(vector) projection** of vector \mathbf{v} onto vector \mathbf{w} is defined by:

$$\text{proj}_{\mathbf{w}} \mathbf{v} := \left(\frac{\mathbf{v} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}} \right) \mathbf{w}$$

Definition

The **scalar projection** of vector \mathbf{v} onto vector \mathbf{w} is defined by:

$$\text{comp}_{\mathbf{w}} \mathbf{v} := \pm \|\text{proj}_{\mathbf{w}} \mathbf{v}\|$$

The sign is **positive** if $\mathbf{v} \cdot \mathbf{w} \geq 0$ and **negative** if $\mathbf{v} \cdot \mathbf{w} < 0$

REMARKS:

- "Projection" means "**vector** projection."
- I'll never say "scalar projection." Instead, I'll say "norm of the projection."
- I'll never write $\text{comp}_{\mathbf{w}} \mathbf{v}$. Instead, I'll write $\pm \|\text{proj}_{\mathbf{w}} \mathbf{v}\|$.

Fin

Fin.