

LINEAR SYSTEMS ($Ax = b$): INTRO, INTERPRETATION [LARSON 1.1]

- **SCALAR:** A scalar is a real #: $0, 1, -5, 9/7, 2.4, \sqrt[3]{7}, 6 - \sqrt{2}, \log 7, \pi, e, \sin(\pi/7), \dots$

Complex numbers will never be considered in this course: $3i, 5 - 2i$ where $i := \sqrt{-1}$

- **LINEAR SYSTEMS:**

A $m \times n$ linear system in x_1, x_2, \dots, x_n has the following form:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

where scalars $a_{11}, \dots, a_{1n}, a_{21}, \dots, a_{2n}, \dots, a_{m1}, \dots, a_{mn} \in \mathbb{R}$

and the RHS scalars $b_1, \dots, b_m \in \mathbb{R}$. [RHS \equiv "Right-Hand Side"]

The **unknown variables** are x_1, \dots, x_n , and appear only to the first power.

i.e., a $m \times n$ linear system has m linear equations & n unknown variables.

- **NON-LINEAR SYSTEMS:**

A system of equations which is not linear is called a **nonlinear system**.

Occasionally, it's possible to convert a nonlinear system into a linear system by a **change of variables (CV)**:

CV: Let $u = 1/x$ and $v = \sqrt{y}$. Then: $\begin{cases} 4/x - 3\sqrt{y} = 1 \\ -1/x + \pi\sqrt{y} = 0 \end{cases} \xLeftrightarrow{CV} \begin{cases} 4u - 3v = 1 \\ -u + \pi v = 0 \end{cases}$

- **UNDERDETERMINED, OVERDETERMINED, SQUARE LINEAR SYSTEMS:**

A $m \times n$ linear system is **underdetermined** \iff there's more unknowns than equations ($m < n$)

A $m \times n$ linear system is **overdetermined** \iff there's more equations than unknowns ($m > n$)

A $m \times n$ linear system is **square** \iff there's as many equations as unknowns ($m = n$)

- **QUALITATIVE SOLUTION POSSIBILITIES FOR LINEAR SYSTEMS:**

For a $m \times n$ linear system, exactly one of the following is true:

- The linear system has a **unique solution** (i.e. one and only one solution)
- The linear system has **infinitely many solutions**
- The linear system has **no solution**

- **CONSISTENT & INCONSISTENT LINEAR SYSTEMS:**

A $m \times n$ linear system is **inconsistent** \iff it has **no solution**. Otherwise, the linear system is called **consistent**.

- **MATRICES, ROW VECTORS, COLUMN VECTORS:**

- A $m \times n$ **matrix** is an array of scalars arranged in m rows & n columns. e.g. $\begin{bmatrix} 1 & 4 & 0 \\ -1 & \pi & (8 - 3\sqrt{5}) \end{bmatrix}$
- A **square matrix** is a matrix with as many rows as columns ($m = n$). e.g. $\begin{bmatrix} \sqrt[3]{2} & 3/4 \\ 1 & 0 \end{bmatrix}$
- A **n -wide row vector** is a $1 \times n$ matrix (i.e. only one row) e.g. $\begin{bmatrix} -3 & 7 & 0 & \sqrt{3} \end{bmatrix}$
- A **m -wide column vector** is a $m \times 1$ matrix (i.e. only one column) e.g. $\begin{bmatrix} 7/5 \\ 1 \end{bmatrix}$

- **WRITING LINEAR SYSTEM IN MATRIX-VECTOR FORM:**

The above prototype $m \times n$ linear system can be written compactly as $Ax = b$,

where A is $m \times n$ **matrix**, x is a n -wide **column vector**, and b is a m -wide **column vector**.

- **WRITING LINEAR SYSTEM AS AUGMENTED MATRIX:**

A linear system $Ax = b$ can be written compactly as $[A | b]$: e.g. $\begin{cases} x - y = 5 \\ 2x + y = \sqrt[3]{9} \end{cases} \iff \left[\begin{array}{cc|c} 1 & -1 & 5 \\ 2 & 1 & \sqrt[3]{9} \end{array} \right]$