

**EX 1.2.3:**

Using Gauss-Jordan elimination, solve the linear system:

$$\begin{cases} 4x + 4y = 4 \\ 3x + y = 1 \\ 2x + y = 1 \\ 4x + 3y = 3 \end{cases}$$

$$\begin{aligned} [A | \mathbf{b}] &= \left[ \begin{array}{cc|c} 4 & 4 & 4 \\ 3 & 1 & 1 \\ 2 & 1 & 1 \\ 4 & 3 & 3 \end{array} \right] \xrightarrow{(\frac{1}{4})R_1 \rightarrow R_1} \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 3 & 1 & 1 \\ 2 & 1 & 1 \\ 4 & 3 & 3 \end{array} \right] \xrightarrow{\begin{array}{l} (-3)R_1 + R_2 \rightarrow R_2 \\ (-2)R_1 + R_3 \rightarrow R_3 \\ (-4)R_1 + R_4 \rightarrow R_4 \end{array}} \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & -2 & -2 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{array} \right] \\ &\xrightarrow{(-\frac{1}{2})R_2 \rightarrow R_2} \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{array} \right] \xrightarrow{\begin{array}{l} R_2 + R_3 \rightarrow R_3 \\ R_2 + R_4 \rightarrow R_4 \end{array}} \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \xrightarrow{(-1)R_2 + R_1 \rightarrow R_1} \left[ \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] = [ \text{RREF}(A) | \tilde{\mathbf{b}} ] \end{aligned}$$

Notice that rows 3 & 4 of RREF(A) are TAUTOLOGIES, since they each translate to the equation  $0 = 0$ .

Remember, nothing special is done when encountering TAUTOLOGIES - just think "Oh, that's nice." and carry on.

Identify the **free** & **fixed** variables:Every column of RREF(A) has pivot  $\implies$  all unknowns  $x, y$  are **fixed variables** (there are no **free variables**)

Qualitatively describe the solution(s) to the linear system:

Since there's no CONTRADICTION's & **every unknown is a fixed variable**, the linear system has a **unique solution**.

Find the solution(s) to the linear system:

Translate  $[ \text{RREF}(A) | \tilde{\mathbf{b}} ]$  into an equivalent linear system:

$$\left[ \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \iff \begin{cases} x = 0 \\ y = 1 \\ 0 = 0 \\ 0 = 0 \end{cases} \iff \begin{cases} x = 0 \\ y = 1 \end{cases}$$

$$\therefore \text{ (TUPLE FORM) } \boxed{(x, y) = (0, 1)} \quad \text{OR} \quad \text{ (COLUMN VECTOR FORM) } \boxed{\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}}$$

**EX 1.2.4:**

Using Gauss-Jordan elimination, solve the linear system:

$$\begin{cases} -x_1 + 3x_2 = -1 \\ 3x_1 - 4x_2 = -1 \\ -3x_1 + 2x_2 = 4 \\ -9x_1 + 6x_2 = -3 \end{cases}$$

$$\begin{aligned} [A | \mathbf{b}] &= \left[ \begin{array}{cc|c} -1 & 3 & -1 \\ 3 & -4 & -1 \\ -3 & 2 & 4 \\ -9 & 6 & -3 \end{array} \right] \xrightarrow{(-1)R_1 \rightarrow R_1} \left[ \begin{array}{cc|c} 1 & -3 & 1 \\ 3 & -4 & -1 \\ -3 & 2 & 4 \\ -9 & 6 & -3 \end{array} \right] \xrightarrow{\begin{array}{l} (-3)R_1 + R_2 \rightarrow R_2 \\ (3)R_1 + R_3 \rightarrow R_3 \\ (9)R_1 + R_4 \rightarrow R_4 \end{array}} \left[ \begin{array}{cc|c} 1 & -3 & 1 \\ 0 & 5 & -4 \\ 0 & -7 & 7 \\ 0 & -21 & 6 \end{array} \right] \\ &\xrightarrow{R_2 \leftrightarrow R_3} \left[ \begin{array}{cc|c} 1 & -3 & 1 \\ 0 & -7 & 7 \\ 0 & 5 & -4 \\ 0 & -21 & 6 \end{array} \right] \xrightarrow{(-\frac{1}{7})R_2 \rightarrow R_2} \left[ \begin{array}{cc|c} 1 & -3 & 1 \\ 0 & 1 & -1 \\ 0 & 5 & -4 \\ 0 & -21 & 6 \end{array} \right] \xrightarrow{\begin{array}{l} (-5)R_2 + R_3 \rightarrow R_3 \\ (21)R_2 + R_4 \rightarrow R_4 \end{array}} \left[ \begin{array}{cc|c} 1 & -3 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \\ 0 & 0 & -15 \end{array} \right] \begin{array}{l} \leftarrow \text{CONTRADICTION!} \\ \leftarrow \text{CONTRADICTION!} \end{array} \end{aligned}$$

 $\therefore$  Since there's at least one CONTRADICTION, the linear system has **no solution**

**EX 1.2.5:**

Using Gauss-Jordan elimination, solve the linear system:

$$\begin{cases} -x_1 + 2x_2 = -1 \\ x_1 - 2x_2 = 1 \\ 3x_1 - 6x_2 = 3 \\ -4x_1 + 8x_2 = -4 \end{cases}$$

$$\left[ A \mid \mathbf{b} \right] = \left[ \begin{array}{cc|c} -1 & 2 & -1 \\ 1 & -2 & 1 \\ 3 & -6 & 3 \\ -4 & 8 & -4 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \left[ \begin{array}{cc|c} 1 & -2 & 1 \\ -1 & 2 & -1 \\ 3 & -6 & 3 \\ -4 & 8 & -4 \end{array} \right] \xrightarrow{\begin{array}{l} R_1 + R_2 \rightarrow R_2 \\ (-3)R_1 + R_3 \rightarrow R_3 \\ 4R_1 + R_4 \rightarrow R_4 \end{array}} \left[ \begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] = \left[ \text{RREF}(A) \mid \tilde{\mathbf{b}} \right]$$

Notice that rows 2,3,4 of  $\text{RREF}(A)$  are TAUTOLOGIES, since they each translate to the equation  $0 = 0$ .

Remember, nothing special is done when encountering a TAUTOLOGY - just think "Oh, that's nice." and carry on.

Identify the **free** & **fixed** variables:

Column 2 of  $\text{RREF}(A)$  has **no pivot**  $\implies$  Unknown  $x_2$  is a **free variable**.

Column 1 of  $\text{RREF}(A)$  has a pivot  $\implies$  Unknown  $x_1$  is a **fixed variable**.

Qualitatively describe the solution(s) to the linear system:

Since there's no CONTRADICTIONS & there's at least one **free variable**, there are **infinitely many solutions**.

Since there's **2 unknowns** ( $x_1, x_2$ ) & **one free variable** ( $x_2$ ), all solutions lie on a **line** in **2-dimensional** space.

Find the solution(s) to the linear system:

Assign a **unique parameter** to each **free variable**: Let  $x_2 = t \in \mathbb{R}$

Express all **fixed variables** in terms of the **parameters** by translating  $\left[ \text{RREF}(A) \mid \tilde{\mathbf{b}} \right]$  into equivalent linear system:

$$\left[ \begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \iff \begin{cases} x_1 - 2x_2 = 1 \\ 0 = 0 \\ 0 = 0 \\ 0 = 0 \end{cases} \iff x_1 - 2t = 1 \iff x_1 = 1 + 2t$$

$$\therefore \text{ (TUPLE FORM) } \boxed{(x_1, x_2) = (1 + 2t, t)}$$

————— OR —————

$$\therefore \text{ (COLUMN VECTOR FORM) } \boxed{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 + 2t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 2 \\ 1 \end{bmatrix}}$$

These two forms of the solution are shown because each WeBWorK problem will demand one form or the other.

On exams, either form is fine with me.

**EX 1.2.6:**

Using Gauss-Jordan elimination, solve the linear system: 
$$\begin{cases} -3x_4 = 2 \\ -2x_1 - 4x_3 + 4x_4 = 1 \\ 2x_1 - x_2 + 4x_3 - 3x_4 = -1 \end{cases}$$

**IMPORTANT:** Since the (1,1)-entry of  $[A \mid \mathbf{b}]$  is **zero**, perform a **SWAP** first!

$$[A \mid \mathbf{b}] = \left[ \begin{array}{cccc|c} 0 & 0 & 0 & -3 & 2 \\ -2 & 0 & -4 & 4 & 1 \\ 2 & -1 & 4 & -3 & -1 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_3} \left[ \begin{array}{cccc|c} 2 & -1 & 4 & -3 & -1 \\ -2 & 0 & -4 & 4 & 1 \\ 0 & 0 & 0 & -3 & 2 \end{array} \right]$$

$$\xrightarrow{R_1+R_2 \rightarrow R_2} \left[ \begin{array}{cccc|c} 2 & -1 & 4 & -3 & -1 \\ 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & -3 & 2 \end{array} \right] \xrightarrow{\begin{array}{l} (\frac{1}{2})R_1 \rightarrow R_1 \\ (-1)R_2 \rightarrow R_2 \\ (-\frac{1}{3})R_3 \rightarrow R_3 \end{array}} \left[ \begin{array}{cccc|c} \boxed{1} & -1/2 & 2 & -3/2 & -1/2 \\ 0 & \boxed{1} & 0 & -1 & 0 \\ 0 & 0 & 0 & \boxed{1} & -2/3 \end{array} \right]$$

$$\xrightarrow{\begin{array}{l} R_3+R_2 \rightarrow R_2 \\ (\frac{3}{2})R_3+R_1 \rightarrow R_1 \end{array}} \left[ \begin{array}{cccc|c} \boxed{1} & -1/2 & 2 & 0 & -3/2 \\ 0 & \boxed{1} & 0 & 0 & -2/3 \\ 0 & 0 & 0 & \boxed{1} & -2/3 \end{array} \right] \xrightarrow{(\frac{1}{2})R_2+R_1 \rightarrow R_1} \left[ \begin{array}{cccc|c} \boxed{1} & 0 & 2 & 0 & -11/6 \\ 0 & \boxed{1} & 0 & 0 & -2/3 \\ 0 & 0 & 0 & \boxed{1} & -2/3 \end{array} \right] = [RREF(A) \mid \tilde{\mathbf{b}}]$$

Identify the **free** & **fixed** variables:

Column 3 of RREF(A) has **no pivot**  $\implies$  Unknown  $x_3$  is a **free variable**.  
 Columns 1,2,4 of RREF(A) each have a pivot  $\implies$  Unknowns  $x_1, x_2, x_4$  are **fixed variables**.

Qualitatively describe the solution(s) to the linear system:

Since there's no **CONTRADICTIONS** & there's at least one **free variable**, there are **infinitely many solutions**.  
 Since there's **4 unknowns** ( $x_1, x_2, x_3, x_4$ ) & **one free variable** ( $x_3$ ), all solutions lie on a **line** in 4-dimensional space.

Find the solution(s) to the linear system:

Assign a **unique parameter** to each **free variable**: Let  $x_3 = t \in \mathbb{R}$

Express all **fixed variables** in terms of the **parameters** by translating  $[RREF(A) \mid \tilde{\mathbf{b}}]$  into equivalent linear system:

$$\left[ \begin{array}{cccc|c} \boxed{1} & 0 & 2 & 0 & -11/6 \\ 0 & \boxed{1} & 0 & 0 & -2/3 \\ 0 & 0 & 0 & \boxed{1} & -2/3 \end{array} \right] \iff \begin{cases} x_1 + 2x_3 = -11/6 \\ x_2 = -2/3 \\ x_4 = -2/3 \end{cases} \iff \begin{cases} x_1 + 2t = -11/6 \\ x_2 = -2/3 \\ x_4 = -2/3 \end{cases}$$

$$\therefore \text{ (TUPLE FORM) } (x_1, x_2, x_3, x_4) = \left( -\frac{11}{6} - 2t, -\frac{2}{3}, t, -\frac{2}{3} \right)$$

————— OR —————

$$\therefore \text{ (COLUMN VECTOR FORM) } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -\frac{11}{6} - 2t \\ -\frac{2}{3} \\ t \\ -\frac{2}{3} \end{bmatrix} = \begin{bmatrix} -\frac{11}{6} \\ -\frac{2}{3} \\ 0 \\ -\frac{2}{3} \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

These two forms of the solution are shown because each WeBWorK problem will demand one form or the other.  
 On exams, either form is fine with me.

**EX 1.2.7:**

Using Gauss-Jordan elimination, solve the linear system: 
$$\begin{cases} x_1 - x_2 & = 0 \\ -2x_2 & - 2x_3 = 0 \\ -x_2 - x_3 & = 0 \end{cases}$$

$$\begin{aligned} [A \mid \mathbf{b}] &= \left[ \begin{array}{ccc|c} \boxed{1} & -1 & 0 & 0 \\ -2 & 0 & -2 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right] \xrightarrow{2R_1+R_2 \rightarrow R_2} \left[ \begin{array}{ccc|c} \boxed{1} & -1 & 0 & 0 \\ 0 & -2 & -2 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right] \xrightarrow{(-\frac{1}{2})R_2 \rightarrow R_2} \left[ \begin{array}{ccc|c} \boxed{1} & -1 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & -1 & -1 & 0 \end{array} \right] \\ &\xrightarrow{R_2+R_3 \rightarrow R_3} \left[ \begin{array}{ccc|c} \boxed{1} & -1 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_2+R_1 \rightarrow R_1} \left[ \begin{array}{ccc|c} \boxed{1} & 0 & 1 & 0 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] = [ \text{RREF}(A) \mid \tilde{\mathbf{b}} ] \end{aligned}$$

Notice that row 3 of  $\text{RREF}(A)$  is a TAUTOLOGY, since it translates to the equation  $0 = 0$ .

Remember, nothing special is done when encountering a TAUTOLOGY - just think "Oh, that's nice." and carry on.

Identify the **free** & **fixed** variables:

Column 3 of  $\text{RREF}(A)$  has **no pivot**  $\implies$  Unknown  $x_3$  is a **free variable**.  
 Columns 1,2 of  $\text{RREF}(A)$  each have a pivot  $\implies$  Unknowns  $x_1, x_2$  are **fixed variables**.

Qualitatively describe the solution(s) to the linear system:

Since there's no CONTRADICTIONS & there's at least one **free variable**, there are **infinitely many solutions**.

Since there's **3 unknowns** ( $x_1, x_2, x_3$ ) & **one free variable** ( $x_3$ ), all solutions lie on a **line** in **3-dimensional** space.

Find the solution(s) to the linear system:

Assign a **unique parameter** to each **free variable**: Let  $x_3 = t \in \mathbb{R}$

Express all **fixed variables** in terms of the **parameters** by translating  $[ \text{RREF}(A) \mid \tilde{\mathbf{b}} ]$  into equivalent linear system:

$$\left[ \begin{array}{ccc|c} \boxed{1} & 0 & 1 & 0 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \iff \begin{cases} x_1 + x_3 = 0 \\ x_2 + x_3 = 0 \\ 0 = 0 \end{cases} \iff \begin{cases} x_1 + t = 0 \\ x_2 + t = 0 \end{cases} \iff \begin{cases} x_1 = -t \\ x_2 = -t \end{cases}$$

$\therefore$  (TUPLE FORM)  $(x_1, x_2, x_3) = (-t, -t, t)$

OR

$$\therefore \text{ (COLUMN VECTOR FORM) } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -t \\ -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

These two forms of the solution are shown because each WeBWorK problem will demand one form or the other.

On exams, either form is fine with me.

**EX 1.2.8:**

Using Gauss-Jordan elimination, solve the linear system: 
$$\begin{cases} x_1 + 2x_2 - 3x_3 = 0 \\ 2x_1 + 4x_2 - 6x_3 = 0 \\ -3x_1 - 6x_2 + 9x_3 = 0 \end{cases}$$

$$\left[ A \mid \mathbf{b} \right] = \left[ \begin{array}{ccc|c} \boxed{1} & 2 & -3 & 0 \\ 2 & 4 & -6 & 0 \\ -3 & -6 & 9 & 0 \end{array} \right] \xrightarrow[\substack{(-2)R_1+R_2 \rightarrow R_2 \\ 3R_1+R_3 \rightarrow R_3}]{\phantom{}} \left[ \begin{array}{ccc|c} \boxed{1} & 2 & -3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] = \left[ \text{RREF}(A) \mid \tilde{\mathbf{b}} \right]$$

Notice that rows 2 & 3 of RREF(A) are TAUTOLOGIES, since they each translate to the equation  $0 = 0$ .

Remember, nothing special is done when encountering TAUTOLOGIES - just think "Oh, that's nice." and carry on.

Identify the **free** & **fixed** variables:

Columns 2,3 of RREF(A) each have **no pivot**  $\implies$  Unknowns  $x_2, x_3$  are **free variables**.

Columns 1 of RREF(A) has a pivot  $\implies$  Unknown  $x_1$  is a **fixed variable**.

Qualitatively describe the solution(s) to the linear system:

Since there's no CONTRADICTIONS & there's at least one **free variable**, there are **infinitely many solutions**.

Since there's **3 unknowns** ( $x_1, x_2, x_3$ ) & **two free variables** ( $x_2, x_3$ ), all solutions lie on a plane in **3-dimensional** space.

Find the solution(s) to the linear system:

Assign a **unique parameter** to each **free variable**: Let  $x_2 = s \in \mathbb{R}$

Let  $x_3 = t \in \mathbb{R}$

Express all **fixed variables** in terms of the **parameters** by translating  $\left[ \text{RREF}(A) \mid \tilde{\mathbf{b}} \right]$  into equivalent linear system:

$$\left[ \begin{array}{ccc|c} \boxed{1} & 2 & -3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \iff \begin{cases} x_1 + 2x_2 - 3x_3 = 0 \\ 0 = 0 \\ 0 = 0 \end{cases} \iff \begin{cases} x_1 + 2s - 3t = 0 \\ 0 = 0 \\ 0 = 0 \end{cases} \iff x_1 = -2s + 3t$$

$$\therefore \boxed{(x_1, x_2, x_3) = (-2s + 3t, s, t)} \text{ OR } \boxed{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2s + 3t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}}$$