EX 2.3.1: Let
$$A = \begin{bmatrix} 1 & -1 \\ 2 & 4 \end{bmatrix}$$
.

(a) Find A^{-1} .

Since A is 2×2 , don't bother with Gauss-Jordan Elimination. Instead use the easier formula:

$$A^{-1} = \frac{1}{(1)(4) - (-1)(2)} \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 2/3 & 1/6 \\ -1/3 & 1/6 \end{bmatrix}$$

(b) Use A^{-1} to solve $A\mathbf{x} = \mathbf{b}$, where $\mathbf{b} = \begin{bmatrix} 1\\ 3 \end{bmatrix}$.

$$A\mathbf{x} = \mathbf{b} \implies \mathbf{x} = A^{-1}\mathbf{b} = \frac{1}{6} \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} (4)(1) + (1)(3) \\ (-2)(1) + (1)(3) \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 7 \\ 1 \end{bmatrix} = \begin{bmatrix} 7/6 \\ 1/6 \end{bmatrix}$$

REMARK: Notice that $\frac{1}{6}$ was factored from A^{-1} to avoid messy fraction arithmetic when multiplying.

(c) Use A^{-1} to solve $A\mathbf{x} = \mathbf{b}$, where $\mathbf{b} = \begin{bmatrix} -2 \\ -1 \end{bmatrix}$.

$$A\mathbf{x} = \mathbf{b} \implies \mathbf{x} = A^{-1}\mathbf{b} = \frac{1}{6} \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} (4)(-2) + (1)(-1) \\ (-2)(-2) + (1)(-1) \end{bmatrix} = \frac{1}{6} \begin{bmatrix} -9 \\ 3 \end{bmatrix} = \begin{bmatrix} -3/2 \\ 1/2 \end{bmatrix}$$

REMARK: Notice that $\frac{1}{6}$ was factored from A^{-1} to avoid messy fraction arithmetic when multiplying.

(d) Use
$$A^{-1}$$
 to solve $AX = B$, where $B = \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix}$.
 $AX = B \implies X = A^{-1}B = \frac{1}{6} \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 4 & 22 \\ -2 & -8 \end{bmatrix} = \boxed{\begin{bmatrix} 2/3 & 11/3 \\ -1/3 & -4/3 \end{bmatrix}}$

$$\begin{split} & \begin{array}{l} \textbf{EX 2.3.2:} \\ \textbf{EX 2.3.2:} \\ \textbf{Let } A = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 5 & 4 \\ 3 & 6 & 5 \end{bmatrix}, & \textbf{Find } A^{-1} \text{ if it exists.} \\ & \begin{bmatrix} A | I | = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 3 & 5 & 5 & 4 & 0 & 1 & 0 \\ 3 & 6 & 5 & 0 & 0 & 1 \end{bmatrix} = \frac{(-3)R_1 + R_2 \rightarrow R_2}{(-3)R_1 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & -3 & 1 & 0 \\ 0 & 3 & 2 & -3 & 0 & 1 \end{bmatrix} \frac{3R_2 \rightarrow R_2}{2R_3 \rightarrow R_3} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 6 & 3 & -9 & 3 & 0 \\ 0 & 6 & 4 & -6 & 0 & 2 \end{bmatrix} \\ & \begin{array}{l} (-1)R_2 + R_3 \rightarrow R_3 \\ (-1)R_2 + R_3 \rightarrow R_3 \\ 0 & 0 & 1 & 3 & -3 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 \\ 3 & -3 & 2 \end{bmatrix} \frac{(-3)R_3 + R_2 \rightarrow R_2}{(-1)R_3 + R_1 \rightarrow R_1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 1 & 3 & -3 & 2 \end{bmatrix} \\ & \begin{array}{l} (\frac{1}{3})R_2 \rightarrow R_2 \\ (\frac{1}{3})R_2 \rightarrow R_2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 1 & 3 & -3 & 2 \end{bmatrix} \xrightarrow{(-1)R_2 + R_3 \rightarrow R_4} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 & 3 & -3 & 2 \end{bmatrix} = [I|A^{-1}] \\ & \therefore A^{-1} = \begin{bmatrix} 1 & 1 & -1 \\ -3 & 2 & -1 \\ 3 & -3 & 2 \end{bmatrix} \\ \hline \\ \hline \textbf{EX 2.3.3:} \quad \textbf{Let } A = \begin{bmatrix} 1 & 1 & 2 \\ 3 & 3 & 6 \\ 2 & 4 & 6 \end{bmatrix} , \quad \textbf{Find } A^{-1} \text{ if it exists.} \\ & \begin{bmatrix} A \mid I \end{bmatrix} = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 3 & 3 & 6 \\ 2 & 4 & 6 \end{bmatrix} , \quad \textbf{Find } A^{-1} \text{ if it exists.} \\ & \begin{array}{l} 0 = -3 \\ 0 = -3 \\ \leftarrow \textbf{CONTRADICTION!} \\ 0 = 0 \leftarrow \textbf{TAUTOLOGY} \end{aligned}$$

Therefore, since there's at least one CONTRADICTION, $\operatorname{RREF}(A) \neq I \implies A$ has no inverse $\implies A$ is singular

The point is when performing Gauss-Jordan Elimination on augmented matrix [A|I], if at any point of the procedure you have a row with all zeroes <u>left</u> of the vertical bar and at least one non-zero <u>right</u> of the vertical bar, you can stop and conclude there's at least one CONTRADICTION, hence $RREF(A) \neq I$ which implies the matrix has no inverse.

$$\begin{array}{l} \boxed{\mathbf{EX 2.3.4:}} \quad \text{Let } A^{-1} = \begin{bmatrix} 1 & 0 & 3 \\ -1 & 2 & 2 \\ 1 & 0 & 0 \end{bmatrix} \text{ and } B^{-1} = \begin{bmatrix} -1 & 4 & 4 \\ 0 & -1 & -2 \\ 3 & -2 & 4 \end{bmatrix}. \\ (a) \quad \text{Compute } \left(-\frac{1}{3}A\right)^{-1}. \qquad \left(-\frac{1}{3}A\right)^{-1} \stackrel{I3}{=} (-3)A^{-1} = (-3) \begin{bmatrix} 1 & 0 & 3 \\ -1 & 2 & 2 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} -3 & 0 & -9 \\ 3 & -6 & -6 \\ -3 & 0 & 0 \end{bmatrix} \\ (b) \quad \text{Compute } (B^2)^{-1}. \qquad (B^2)^{-1} \stackrel{I2}{=} (B^{-1})^2 = B^{-1}B^{-1} = \begin{bmatrix} -1 & 4 & 4 \\ 0 & -1 & -2 \\ 3 & -2 & 4 \end{bmatrix} \begin{bmatrix} -1 & 4 & 4 \\ 0 & -1 & -2 \\ 3 & -2 & 4 \end{bmatrix} = \begin{bmatrix} 13 & -16 & 4 \\ -6 & 5 & -6 \\ 9 & 6 & 32 \end{bmatrix} \\ (c) \quad \text{Compute } (AB)^{-1}. \qquad (AB)^{-1} \stackrel{I5}{=} B^{-1}A^{-1} = \begin{bmatrix} -1 & 4 & 4 \\ 0 & -1 & -2 \\ 3 & -2 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 3 \\ -1 & 2 & 2 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 8 & 5 \\ -1 & -2 & -2 \\ 9 & -4 & 5 \end{bmatrix} \end{array}$$

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