

EX 6.3.2: Find std matrix A for linear transformation $L : \mathbb{R}^2 \rightarrow \mathbb{R}^4$ s.t. $L\left(\begin{bmatrix} 1 \\ 4 \end{bmatrix}\right) = \begin{bmatrix} -3 \\ 14 \\ -2 \\ 6 \end{bmatrix}$, $L\left(\begin{bmatrix} 2 \\ -3 \end{bmatrix}\right) = \begin{bmatrix} 16 \\ -5 \\ 7 \\ 12 \end{bmatrix}$

$$\left[\begin{array}{cc|c} \text{---} & \mathbf{b}_1 & \text{---} \\ \text{---} & \mathbf{b}_2 & \text{---} \end{array} \middle| \begin{array}{c} L(\mathbf{b}_1) \\ L(\mathbf{b}_2) \end{array} \right] = \left[\begin{array}{cc|c} \boxed{1} & 4 & (-3, 14, -2, 6)^T \\ 2 & -3 & (16, -5, 7, 12)^T \end{array} \right] \xrightarrow{(-2)\mathbf{R}_1 + \mathbf{R}_2 \rightarrow \mathbf{R}_2} \left[\begin{array}{cc|c} \boxed{1} & 4 & (-3, 14, -2, 6)^T \\ 0 & -11 & (22, -33, 11, 0)^T \end{array} \right]$$

$$\xrightarrow{(-\frac{1}{11})\mathbf{R}_2 \rightarrow \mathbf{R}_2} \left[\begin{array}{cc|c} \boxed{1} & 4 & (-3, 14, -2, 6)^T \\ 0 & \boxed{1} & (-2, 3, -1, 0)^T \end{array} \right] \xrightarrow{(-4)\mathbf{R}_2 + \mathbf{R}_1 \rightarrow \mathbf{R}_1} \left[\begin{array}{cc|c} \boxed{1} & 0 & (5, 2, 2, 6)^T \\ 0 & \boxed{1} & (-2, 3, -1, 0)^T \end{array} \right] = \left[\begin{array}{c|c} I & L(\mathbf{e}_1) \\ & L(\mathbf{e}_2) \end{array} \right]$$

$$\implies A = \left[\begin{array}{cc|c} | & | & | \\ L(\mathbf{e}_1) & L(\mathbf{e}_2) & | \\ | & | & | \end{array} \right] = \left[\begin{array}{cc} 5 & -2 \\ 2 & 3 \\ 2 & -1 \\ 6 & 0 \end{array} \right] \quad \therefore L\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \left[\begin{array}{cc} 5 & -2 \\ 2 & 3 \\ 2 & -1 \\ 6 & 0 \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \left[\begin{array}{c} 5x_1 - 2x_2 \\ 2x_1 + 3x_2 \\ 2x_1 - x_2 \\ 6x_1 \end{array} \right]$$

EX 6.3.3: Find standard matrix A for linear transformation $L : P_2 \rightarrow P_2$ s.t. $L(p) = t^2 p''(t)$.

Find the images of the **standard basis vectors** for the **domain** of L : (Write polynomials in **ascending order**)

$$\begin{aligned} L(\mathbf{e}_1) &= L(1) &= t^2 \frac{d^2}{dt^2}[1] &= 0 &\simeq (0, 0, 0)^T \\ L(\mathbf{e}_2) &= L(t) &= t^2 \frac{d^2}{dt^2}[t] &= 0 &\simeq (0, 0, 0)^T \\ L(\mathbf{e}_3) &= L(t^2) &= t^2 \frac{d^2}{dt^2}[t^2] &= 2t^2 &\simeq (0, 0, 2)^T \end{aligned} \implies A = \left[\begin{array}{ccc|c} | & | & | & | \\ L(\mathbf{e}_1) & L(\mathbf{e}_2) & L(\mathbf{e}_3) & | \\ | & | & | & | \end{array} \right] = \left[\begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{array} \right]$$

$$\therefore L(a + bt + ct^2) \simeq \left[\begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{array} \right] \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2c \end{bmatrix} \simeq 2ct^2$$

EX 6.3.4: Find standard matrix A for linear transformation $L : P_2 \rightarrow P_3$ s.t. $L(p) = \int p(t) dt$. (Do not include '+C')

Find the images of the **standard basis vectors** for the **domain** of L : (Write polynomials in **ascending order**)

$$\begin{aligned} L(\mathbf{e}_1) &= L(1) &= \int 1 dt &= t &\simeq (0, 1, 0, 0)^T \\ L(\mathbf{e}_2) &= L(t) &= \int t dt &= \frac{1}{2}t^2 &\simeq (0, 0, \frac{1}{2}, 0)^T \\ L(\mathbf{e}_3) &= L(t^2) &= \int t^2 dt &= \frac{1}{3}t^3 &\simeq (0, 0, 0, \frac{1}{3})^T \end{aligned} \implies A = \left[\begin{array}{ccc|c} | & | & | & | \\ L(\mathbf{e}_1) & L(\mathbf{e}_2) & L(\mathbf{e}_3) & | \\ | & | & | & | \end{array} \right] = \left[\begin{array}{ccc} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{array} \right]$$

$$\therefore L(a + bt + ct^2) \simeq \left[\begin{array}{ccc} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{array} \right] \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ a \\ b/2 \\ c/3 \end{bmatrix} \simeq at + \frac{1}{2}bt^2 + \frac{1}{3}ct^3$$

EX 6.3.5: Find standard matrix A for linear transformation $L : P_2 \rightarrow \mathbb{R}$ s.t. $L(p) = \int_0^1 p(t) dt$.

Find the images of the **standard basis vectors** for the **domain** of L : (Write polynomials in **ascending order**)

$$\begin{aligned} L(\mathbf{e}_1) &= L(1) &= \int_0^1 1 dt &= \left[t \right]_{t=0}^{t=1} \stackrel{\text{FTC}}{=} (1) - (0) &= 1 \\ L(\mathbf{e}_2) &= L(t) &= \int_0^1 t dt &= \left[\frac{1}{2}t^2 \right]_{t=0}^{t=1} \stackrel{\text{FTC}}{=} \frac{1}{2}(1)^2 - \frac{1}{2}(0)^2 &= \frac{1}{2} \implies A = \left[\begin{array}{ccc} 1 & \frac{1}{2} & \frac{1}{3} \end{array} \right] \\ L(\mathbf{e}_3) &= L(t^2) &= \int_0^1 t^2 dt &= \left[\frac{1}{3}t^3 \right]_{t=0}^{t=1} \stackrel{\text{FTC}}{=} \frac{1}{3}(1)^3 - \frac{1}{3}(0)^3 &= \frac{1}{3} \end{aligned}$$

$$\therefore L(a + bt + ct^2) \simeq \left[\begin{array}{ccc} 1 & \frac{1}{2} & \frac{1}{3} \end{array} \right] \begin{bmatrix} a \\ b \\ c \end{bmatrix} = a + \frac{1}{2}b + \frac{1}{3}c$$