

Linear Transformations: Kernel, Range, 1-1, Onto

Linear Algebra

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Kernel of a Linear Transformation (Definition)

Definition

(Kernel of a Linear Transformation)

Let $L : V \rightarrow W$ be a linear transformation.

Then the **kernel** of L is defined to be:

$$\ker(L) := \{\mathbf{v} \in V : L(\mathbf{v}) = \vec{\mathbf{0}}\} \subseteq V$$

i.e. The kernel of L is the set of all vectors in V that are mapped by L to $\vec{\mathbf{0}}$.

Theorem

(The Kernel of L is a Subspace of V)

Let $L : V \rightarrow W$ be a linear transformation. Then, $\ker(L)$ is a subspace of V .

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Theorem

(The Kernel of L is a Subspace of V)

Let $L : V \rightarrow W$ be a linear transformation. Then, $\ker(L)$ is a subspace of V .

PROOF: $L(\vec{\mathbf{0}}) = \vec{\mathbf{0}} \implies \vec{\mathbf{0}} \in \ker(L) \implies \ker(L)$ is a nonempty subset of V .

$\mathbf{u}, \mathbf{v} \in \ker(L) \implies L(\mathbf{u} + \mathbf{v}) \stackrel{LT1}{=} L(\mathbf{u}) + L(\mathbf{v}) = \vec{\mathbf{0}} + \vec{\mathbf{0}} = \vec{\mathbf{0}} \implies \mathbf{u} + \mathbf{v} \in \ker(L)$

$\alpha \in \mathbb{R}, \mathbf{v} \in \ker(L) \implies L(\alpha\mathbf{v}) \stackrel{LT2}{=} \alpha L(\mathbf{v}) = \alpha(\vec{\mathbf{0}}) = \vec{\mathbf{0}} \implies \alpha\mathbf{v} \in \ker(L)$

$\therefore \ker(L)$ is closed under VA & SM $\implies \ker(L)$ is a subspace of V QED

Range of a Linear Transformation (Definition)

Definition

(Range of a Linear Transformation)

Let $L : V \rightarrow W$ be a linear transformation.
Then the **range** of L is defined to be:

$$\text{range}(L) := \{L(\mathbf{v}) \in W : \mathbf{v} \in V\}$$

Theorem

(The Range of L is a Subspace of W)

Let $L : V \rightarrow W$ be a linear transformation. Then, $\text{range}(L)$ is a subspace of W .

PROOF: $L(\vec{\mathbf{0}}) = \vec{\mathbf{0}} \implies \vec{\mathbf{0}} \in \text{range}(L) \implies \text{range}(L)$ is nonempty subset of W .

$L(\mathbf{u}), L(\mathbf{v}) \in \text{range}(L) \implies \mathbf{u}, \mathbf{v} \in V \implies (\mathbf{u} + \mathbf{v}) \in V \implies L(\mathbf{u} + \mathbf{v}) \in \text{range}(L)$

$\alpha \in \mathbb{R}, L(\mathbf{v}) \in \text{range}(L) \implies \mathbf{v} \in V \implies \alpha\mathbf{v} \in V \implies L(\alpha\mathbf{v}) \in \text{range}(L)$

$\therefore \text{range}(L)$ is closed under VA & SM $\implies \text{range}(L)$ is a subspace of W \square

Ker(L) & Range(L) in terms of Representative Matrix

Corollary

(Relationship between a Linear Transformation and its Representative Matrix)

Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that $L(\mathbf{x}) = A\mathbf{x}$. (where $A \in \mathbb{R}^{m \times n}$) Then:

$$\ker(L) = \text{NulSp}(A) \qquad \text{range}(L) = \text{ColSp}(A)$$

PROOF:

$$\mathbf{x} \in \ker(L) \subseteq \mathbb{R}^n \iff L(\mathbf{x}) = \vec{\mathbf{0}} \iff A\mathbf{x} = \vec{\mathbf{0}} \iff \mathbf{x} \in \text{NulSp}(A)$$

$$L(\mathbf{x}) \in \text{range}(L) \subseteq \mathbb{R}^m \iff \mathbf{x} \in \mathbb{R}^n \iff A\mathbf{x} \in \text{ColSp}(A)$$

Rank & Nullity of a Linear Transformation

Definition

(Rank & Nullity of a Matrix & Linear Transformation)

(i) Let A be an $m \times n$ matrix. Then:

$$\begin{aligned}\text{rank}(A) &= \dim[\text{ColSp}(A)] = (\# \text{ of pivot columns of RREF}(A)) \\ \text{nullity}(A) &= \dim[\text{NulSp}(A)] = (\# \text{ of non-pivot columns of RREF}(A))\end{aligned}$$

(ii) Let $L : V \rightarrow W$ be a linear transformation. Then:

$$\text{rank}(L) = \dim[\text{range}(L)] \qquad \text{nullity}(L) = \dim[\text{ker}(L)]$$

Rank-Nullity Theorem

Theorem

(Rank-Nullity Theorem)

(i) Let A be an $m \times n$ matrix. Then:

$$\text{rank}(A) + \text{nullity}(A) = (\# \text{ of columns of } A)$$

(ii) Let $L : V \rightarrow W$ be a linear transformation. Then:

$$\text{rank}(L) + \text{nullity}(L) = \dim[\text{domain}(L)]$$

Preimage of a Vector (Definition)

Definition

(Preimage of a Vector)

Let $T : V \rightarrow W$ be a transformation. Then the **preimage** of vector $\mathbf{w} \in W$ is:

$$\text{Preimage}(\mathbf{w}) := \{\mathbf{v} \in V : T(\mathbf{v}) = \mathbf{w}\} \subseteq V$$

1-1 Linear Transformations (Definition)

Definition

(1-1 Transformation)

Let $T : V \rightarrow W$ be a transformation. Then:

$$T \text{ is } \mathbf{1-1} \text{ (one-to-one)} \iff \forall \mathbf{u}, \mathbf{v} \in V, T(\mathbf{u}) = T(\mathbf{v}) \implies \mathbf{u} = \mathbf{v}.$$

Definition

(1-1 Linear Transformation)

Let $L : V \rightarrow W$ be a linear transformation. Then, L is 1-1 $\iff \ker(L) = \{\vec{\mathbf{0}}\}$.

Onto Linear Transformations (Definition)

Definition

(Onto Transformation)

Let $T : V \rightarrow W$ be a transformation. Then, T is **onto** $\iff \text{range}(T) = W$.

Definition

(Onto Linear Transformation)

Let $L : V \rightarrow W$ be a linear transformation such that W is finite-dimensional. Then, L is onto $\iff \text{rank}(L) = \dim(W)$.

Isomorphisms (Definition)

Definition

(Isomorphism)

Let $L : V \rightarrow W$ be a linear transformation.

Then, L is called an **isomorphism** if L is 1-1 and onto.

Moreover, vector spaces V, W are said to be **isomorphic** (to each other) if there exists an isomorphism from V to W .

Theorem

(Finite-dimensional Isomorphic Spaces have the same Dimension)

Let V, W be finite-dimensional vector spaces.

Then, V & W are isomorphic $\iff \dim(V) = \dim(W)$

PROOF: See the textbook if interested.

Isomorphisms (Examples)

Vector spaces \mathbb{R}^4 , $\mathbb{R}^{2 \times 2}$, P_3 are all isomorphic to each other since there exists isomorphisms L_1, L_2 as shown below:

$$\text{Let } L_1 : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^4 \text{ s.t. } L_1 \left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \right) = \begin{bmatrix} a_{11} \\ a_{12} \\ a_{21} \\ a_{22} \end{bmatrix}$$

$$\text{Let } L_2 : P_3 \rightarrow \mathbb{R}^4 \text{ s.t. } L_2 (a_0 + a_1x + a_2x^2 + a_3x^3) = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

Isomorphic vector spaces are essentially "the same" but with representations by different mathematical objects (vectors, matrices, polynomials.)

In particular, matrices & polynomials can be represented by vectors, which will be quite useful in the next two sections....

Fin

Fin.