

Symmetric Matrices, Orthogonal Matrices

Linear Algebra

Josh Engwer

TTU

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PART I:
SYMMETRIC MATRICES
ORTHOGONAL MATRICES

Symmetric Matrices (Definition)

The notion of a symmetric matrix is fundamental for later concepts & courses:

Definition

(Symmetric Matrix)

A square matrix $A \in \mathbb{R}^{n \times n}$ is **symmetric** if A is equal to its transpose: $A^T = A$

Corollary

(Diagonal Matrices are Symmetric)

A diagonal matrix $D \in \mathbb{R}^{n \times n}$ is symmetric.

Symmetric Matrices: $\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$, $\begin{bmatrix} -4 & 0 \\ 0 & -1 \end{bmatrix}$, $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$

Not Symmetric: $\begin{bmatrix} -4 & 0 \\ 1 & -1 \end{bmatrix}$, $\begin{bmatrix} 1 & 2 & 3 \\ 9 & 4 & 5 \\ 8 & 0 & 6 \end{bmatrix}$, $\begin{bmatrix} 1 & 2 & 3 \\ 9 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$

Symmetric Matrices (Properties)

Symmetric matrices have some very nice properties:

Theorem

(The Real Spectrum Theorem)

Let symmetric matrix $S \in \mathbb{R}^{n \times n}$. Then the following all hold:

- S is diagonalizable
- All eigenvalues of S are real
- If some eigenvalue λ_k repeats, its multiplicities match: $AM[\lambda_k] = GM[\lambda_k]$
i.e. If λ_k occurs j times, then λ_k has j linearly independent eigenvectors:

$$\mathbf{x}_{k,1}, \mathbf{x}_{k,2}, \dots, \mathbf{x}_{k,j-1}, \mathbf{x}_{k,j}$$

PROOF: It's complicated...

Orthogonal Matrices (Definition)

Question: When is the inverse of a square matrix simply its transpose??

Answer: When the square matrix is orthogonal:

Definition

(Orthogonal Matrix)

A square matrix $Q \in \mathbb{R}^{n \times n}$ is **orthogonal** if Q is invertible and $Q^{-1} = Q^T$

Corollary

(Determining if a Matrix is Orthogonal)

A square matrix $Q \in \mathbb{R}^{n \times n}$ is **orthogonal** $\iff Q^T Q = I$

Theorem

(An Orthogonal Matrix has Orthonormal Columns)

A square matrix Q is **orthogonal** \iff its columns form an orthonormal set.

PROOF: See the textbook if interested.

Orthogonal Matrices (Properties)

The following theorem is the cornerstone to many stable numerical algorithms involving orthogonal matrices:

Theorem

(Orthogonal Preservation Theorem)

Consider the Euclidean inner product space $(\mathbb{R}^n, \langle \cdot, \cdot \rangle)$ where $\mathbf{v}, \mathbf{w}, \mathbf{x} \in \mathbb{R}^n$ and

$$\begin{array}{lll} \text{Inner product} & \langle \mathbf{v}, \mathbf{w} \rangle & := \mathbf{v}^T \mathbf{w} \\ \text{Induced norm} & \|\mathbf{x}\| & := \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle} \\ \text{Induced metric} & d(\mathbf{v}, \mathbf{w}) & := \|\mathbf{v} - \mathbf{w}\| \end{array}$$

Then orthogonal matrix $Q \in \mathbb{R}^{n \times n}$ preserves inner products, norms & metrics:

$$(i) \langle Q\mathbf{v}, Q\mathbf{w} \rangle = \langle \mathbf{v}, \mathbf{w} \rangle, \quad (ii) \|Q\mathbf{x}\| = \|\mathbf{x}\|, \quad (iii) d(Q\mathbf{v}, Q\mathbf{w}) = d(\mathbf{v}, \mathbf{w})$$

Orthogonal Matrices (Properties)

Theorem

(Orthogonal Preservation Theorem)

Consider the Euclidean inner product space $(\mathbb{R}^n, \langle \cdot, \cdot \rangle)$ where $\mathbf{v}, \mathbf{w}, \mathbf{x} \in \mathbb{R}^n$ and

$$\begin{aligned} \text{Inner product} \quad \langle \mathbf{v}, \mathbf{w} \rangle &:= \mathbf{v}^T \mathbf{w} \\ \text{Induced norm} \quad \|\mathbf{x}\| &:= \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle} \\ \text{Induced metric} \quad d(\mathbf{v}, \mathbf{w}) &:= \|\mathbf{v} - \mathbf{w}\| \end{aligned}$$

Then orthogonal matrix $Q \in \mathbb{R}^{n \times n}$ preserves inner products, norms & metrics:

$$(i) \langle Q\mathbf{v}, Q\mathbf{w} \rangle = \langle \mathbf{v}, \mathbf{w} \rangle, \quad (ii) \|Q\mathbf{x}\| = \|\mathbf{x}\|, \quad (iii) d(Q\mathbf{v}, Q\mathbf{w}) = d(\mathbf{v}, \mathbf{w})$$

PROOF:

$$(i) \langle Q\mathbf{v}, Q\mathbf{w} \rangle := (Q\mathbf{v})^T (Q\mathbf{w}) \stackrel{T4}{=} \mathbf{v}^T (Q^T Q) \mathbf{w} = \mathbf{v}^T (Q^{-1} Q) \mathbf{w} = \mathbf{v}^T I \mathbf{w} = \mathbf{v}^T \mathbf{w} := \langle \mathbf{v}, \mathbf{w} \rangle$$

$$(ii) \|Q\mathbf{x}\|^2 = \langle Q\mathbf{x}, Q\mathbf{x} \rangle \stackrel{(i)}{=} \langle \mathbf{x}, \mathbf{x} \rangle = \|\mathbf{x}\|^2 \implies \|Q\mathbf{x}\| = \|\mathbf{x}\|$$

$$(iii) d(Q\mathbf{v}, Q\mathbf{w}) := \|Q\mathbf{v} - Q\mathbf{w}\| \stackrel{M3}{=} \|Q(\mathbf{v} - \mathbf{w})\| \stackrel{(ii)}{=} \|\mathbf{v} - \mathbf{w}\|$$

QED

Eigenvectors of a Symmetric Matrix

Eigenvectors of distinct eigenvalues of a symmetric matrix have a benefit:

Theorem

(Eigenvectors of a Symmetric Matrix)

Let symmetric matrix $S \in \mathbb{R}^{n \times n}$ have eigenpairs $(\lambda_1, \mathbf{x}_1), (\lambda_2, \mathbf{x}_2)$. Then:

If eigenvalues λ_1, λ_2 are distinct, then eigenvectors $\mathbf{x}_1, \mathbf{x}_2$ are orthogonal.

i.e. If $\lambda_1 \neq \lambda_2$, then $\mathbf{x}_1 \perp \mathbf{x}_2$.

Eigenvectors of a Symmetric Matrix

Theorem

(Eigenvectors of a Symmetric Matrix)

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If eigenvalues λ_1, λ_2 are distinct, then eigenvectors $\mathbf{x}_1, \mathbf{x}_2$ are orthogonal.

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PROOF: Let $\begin{pmatrix} (\lambda_1, \mathbf{x}_1) \\ (\lambda_2, \mathbf{x}_2) \end{pmatrix}$ be eigenpairs of S s.t. $\lambda_1 \neq \lambda_2$. Then $\begin{matrix} S\mathbf{x}_1 = \lambda_1\mathbf{x}_1 \\ S\mathbf{x}_2 = \lambda_2\mathbf{x}_2 \end{matrix}$

Moreover: (Since S is symmetric, $S = S^T$)

$$\lambda_1(\mathbf{x}_1^T \mathbf{x}_2) = (\lambda_1 \mathbf{x}_1)^T \mathbf{x}_2 \stackrel{EIG}{=} (S\mathbf{x}_1)^T \mathbf{x}_2 \stackrel{T4}{=} \mathbf{x}_1^T S^T \mathbf{x}_2 \stackrel{SYM}{=} \mathbf{x}_1^T (S\mathbf{x}_2) \stackrel{EIG}{=} \mathbf{x}_1^T (\lambda_2 \mathbf{x}_2) = \lambda_2(\mathbf{x}_1^T \mathbf{x}_2)$$

Hence:

$$\lambda_1(\mathbf{x}_1^T \mathbf{x}_2) = \lambda_2(\mathbf{x}_1^T \mathbf{x}_2) \implies \lambda_1(\mathbf{x}_1^T \mathbf{x}_2) - \lambda_2(\mathbf{x}_1^T \mathbf{x}_2) = 0 \implies (\lambda_1 - \lambda_2)(\mathbf{x}_1^T \mathbf{x}_2) = 0$$

Since $\lambda_1 \neq \lambda_2 \iff \lambda_1 - \lambda_2 \neq 0$, the equation $(\lambda_1 - \lambda_2)(\mathbf{x}_1^T \mathbf{x}_2) = 0$ implies that $\mathbf{x}_1^T \mathbf{x}_2 = 0 \implies \mathbf{x}_1 \perp \mathbf{x}_2 \implies \mathbf{x}_1, \mathbf{x}_2$ are orthogonal QED

PART II:
ORTHOGONAL DIAGONALIZATION
OF A
SYMMETRIC MATRIX

Orthogonally Diagonalizable Matrices

Definition

(Orthogonally Diagonalizable Matrix)

Let square matrix $A \in \mathbb{R}^{n \times n}$.

Then A is **orthogonally diagonalizable** if $\exists Q \in \mathbb{R}^{n \times n}$ s.t. Q is orthogonal and

$$Q^T A Q = D \text{ where } D \text{ is diagonal.}$$

Theorem

(Symmetric Matrices are Orthogonally Diagonalizable)

Square matrix A is orthogonally diagonalizable $\iff A$ is symmetric.

PROOF: (\implies): Let A be orthogonally diagonalizable.

Then $Q^T A Q = D$ for some orthogonal matrix Q and diagonal matrix D .

$$\text{Now, } Q^T A Q = D \implies Q Q^T A Q Q^T = Q D Q^T \implies I A I = Q D Q^T \implies A = Q D Q^T$$

$$\text{Now, } A^T = (Q D Q^T)^T \stackrel{T^4}{=} Q^{TT} D^T Q^T = Q D^T Q^T \stackrel{SYM}{=} Q D Q^T = A$$

$$\therefore A^T = A \implies A \text{ is symmetric}$$

(\impliedby): It's subtle – see the textbook if interested.

QED

Orthogonal Diagonalization of a Symmetric Matrix

Proposition

(Orthogonally Diagonalizing a Symmetric Matrix)

GIVEN: Symmetric Matrix $S \in \mathbb{R}^{n \times n}$ with some possibly repeated eigenvalues.

TASK: Orthogonally Diagonalize Symmetric Matrix S .

- (1) Find the Eigenvalues of S : $\lambda_1, \dots, \lambda_n$
- (2) Find the Eigenspace E_{λ_k} for each unique Eigenvalue λ_k .
- (3) Find Unit Eigenvector(s) $\hat{\mathbf{q}}_k$ for each unique Eigenvalue λ_k : $\hat{\mathbf{q}}_k = \frac{\mathbf{q}_k}{\|\mathbf{q}_k\|}$
If $AM[\lambda_k] \geq 2$, then apply Gram-Schmidt on the eigenvectors for λ_k .
- (4) Let matrix $Q \in \mathbb{R}^{n \times n}$ s.t. its columns consist of the unit eigenvectors.
- (5) Let diagonal matrix $\Lambda \in \mathbb{R}^{n \times n}$ s.t. the eigenvalues are on its main diagonal.
The order of eigenvectors in Q determine the order of eigenvalues in Λ .
- (6) Form the diagonalization of S : $S = Q\Lambda Q^T$

NOTATION: Λ is the capital Greek letter 'lambda'.

Ortho. Diagonalization of Symmetric Matrix (Ordering)

Consistency is key when ordering eigenvalues in Λ & eigenvectors in Q :

Let 3×3 sym. matrix S have eigenvalues $\lambda_1, \lambda_2, \lambda_3$ & eigenvectors $\hat{\mathbf{q}}_1, \hat{\mathbf{q}}_2, \hat{\mathbf{q}}_3$.
Then, S can be orthogonally diagonalized as $S = Q\Lambda Q^T$, where:

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_1 & \hat{\mathbf{q}}_2 & \hat{\mathbf{q}}_3 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_2 & \hat{\mathbf{q}}_1 & \hat{\mathbf{q}}_3 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_2 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_3 & \hat{\mathbf{q}}_1 & \hat{\mathbf{q}}_2 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_3 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_3 & \hat{\mathbf{q}}_2 & \hat{\mathbf{q}}_1 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_3 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_1 \end{bmatrix}$$

Ortho. Diagonalization of Symmetric Matrix (Ordering)

Consistency is key when ordering eigenvalues in Λ & eigenvectors in Q :

Let 3×3 sym. matrix S have eigenvalues λ_1, λ_2 & eigenvectors $\hat{\mathbf{q}}_{1,1}, \hat{\mathbf{q}}_{1,2}, \hat{\mathbf{q}}_2$.
Then, S can be orthogonally diagonalized as $S = Q\Lambda Q^T$, where:

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_{1,1} & \hat{\mathbf{q}}_{1,2} & \hat{\mathbf{q}}_2 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_{1,2} & \hat{\mathbf{q}}_{1,1} & \hat{\mathbf{q}}_2 \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_{1,1} & \hat{\mathbf{q}}_2 & \hat{\mathbf{q}}_{1,2} \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_1 \end{bmatrix}$$

OR

$$Q = \begin{bmatrix} | & | & | \\ \hat{\mathbf{q}}_2 & \hat{\mathbf{q}}_{1,1} & \hat{\mathbf{q}}_{1,2} \\ | & | & | \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} \lambda_2 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_1 \end{bmatrix}$$

Fin.