

# VECTOR FUNCTIONS: CALCULUS & KINEMATICS [SST 10.2]

## • THE FUNCTION LANDSCAPE (SO FAR):

FUNCTION TYPE	PROTOTYPE	MAPPING	MEANING	FIRST SEEN
Scalar Function	$y = f(x)$	$f : \mathbb{R} \rightarrow \mathbb{R}$	$f$ maps scalar $\rightarrow$ scalar	Algebra
3D Vector Function	$\mathbf{F}(t) = \langle f_1(t), f_2(t), f_3(t) \rangle$	$\mathbf{F} : \mathbb{R} \rightarrow \mathbb{R}^3$	$\mathbf{F}$ maps scalar $\rightarrow$ 3D vector	Calc III (Ch10)

## • VECTOR FUNCTIONS (DERIVATIVES):

– LIMIT DEFINITION OF DERIVATIVE:  $\mathbf{F}'(t) := \lim_{\Delta t \rightarrow 0} \frac{\mathbf{F}(t + \Delta t) - \mathbf{F}(t)}{\Delta t}$

ORDER	DEFINITION	LEIBNIZ NOTATION
$1^{st}$ Derivative	$\mathbf{F}'(t) := \langle f_1'(t), f_2'(t), f_3'(t) \rangle$	$\frac{d\mathbf{F}}{dt}$
$2^{nd}$ Derivative	$\mathbf{F}''(t) := \langle f_1''(t), f_2''(t), f_3''(t) \rangle$	$\frac{d^2\mathbf{F}}{dt^2}$
$n^{th}$ Derivative	$\mathbf{F}^{(n)}(t) := \langle f_1^{(n)}(t), f_2^{(n)}(t), f_3^{(n)}(t) \rangle$	$\frac{d^n\mathbf{F}}{dt^n}$

– Vector function  $\mathbf{F}(t)$  is **differentiable on a set**  $S \subseteq \mathbb{R} \iff \mathbf{F} \in C^1(S) \iff$  scalar functions  $f_1, f_2, f_3 \in C^1(S)$

– Vector function  $\mathbf{F}(t)$  is **twice differentiable on a set**  $S \subseteq \mathbb{R} \iff \mathbf{F} \in C^2(S) \iff f_1, f_2, f_3 \in C^2(S)$

DERIVATIVE RULE	FORMULA
Sum/Diff Rule	$\frac{d}{dt} [\mathbf{F}(t) \pm \mathbf{G}(t)] = \mathbf{F}'(t) \pm \mathbf{G}'(t)$
Scalar Multiple Rule	$\frac{d}{dt} [h(t)\mathbf{F}(t)] = h'(t)\mathbf{F}(t) + h(t)\mathbf{F}'(t)$
Dot Product Rule	$\frac{d}{dt} [\mathbf{F}(t) \cdot \mathbf{G}(t)] = \mathbf{F}'(t) \cdot \mathbf{G}(t) + \mathbf{F}(t) \cdot \mathbf{G}'(t)$
Cross Product Rule	$\frac{d}{dt} [\mathbf{F}(t) \times \mathbf{G}(t)] = \mathbf{F}'(t) \times \mathbf{G}(t) + \mathbf{F}(t) \times \mathbf{G}'(t)$
Chain Rule	$\frac{d}{dt} [\mathbf{F}[h(t)]] = \mathbf{F}'[h(t)] h'(t)$

## • SMOOTH CURVES: Let $\Gamma$ be the curve traced by **position vector** $\mathbf{F}(t)$ .

–  $\mathbf{F}(t)$  (curve  $\Gamma$ ) is **smooth on interval**  $(a, b) \iff [\mathbf{F} \in C^1(a, b) \text{ AND } \mathbf{F}'(t) \neq \vec{\mathbf{0}} \quad \forall t \in (a, b)]$

–  $\mathbf{F}(t)$  (curve  $\Gamma$ ) is **piecewise smooth on**  $(a, b) \iff \Gamma$  is smooth on  $(a, b)$  except at a finite # of points.

## • VECTOR FUNCTIONS (KINEMATICS):

– SETUP: Given a **particle** in 3D with **position vector**  $\mathbf{R}(t) = \langle R_1(t), R_2(t), R_3(t) \rangle$

Trajectory			$\Gamma :=$ Graph of position vector $\mathbf{R}(t)$		
Velocity	Speed	Direction	$\mathbf{V}(t) := \mathbf{R}'(t)$	$\ \mathbf{V}(t)\ $	$\frac{\mathbf{V}(t)}{\ \mathbf{V}(t)\ }$
Acceleration Vector			$\mathbf{A}(t) := \mathbf{V}'(t) = \mathbf{R}''(t)$		

– The particle is **stationary**  $\iff \mathbf{V}(t) = \vec{\mathbf{0}}$

## • VECTOR FUNCTIONS (INTEGRALS):

\*  $\int \mathbf{F}(t) dt := \left[ \int f_1(t) dt \right] \hat{\mathbf{i}} + \left[ \int f_2(t) dt \right] \hat{\mathbf{j}} + \left[ \int f_3(t) dt \right] \hat{\mathbf{k}} + \vec{\mathbf{C}}$  , where  $\vec{\mathbf{C}} = \langle C_1, C_2, C_3 \rangle$  is a **constant vector**

\*  $\int_a^b \mathbf{F}(t) dt := \left[ \int_a^b f_1(t) dt \right] \hat{\mathbf{i}} + \left[ \int_a^b f_2(t) dt \right] \hat{\mathbf{j}} + \left[ \int_a^b f_3(t) dt \right] \hat{\mathbf{k}}$

**EX 10.2.1:** Let  $\mathbf{F}(t) = \langle 1, t, t^5 \rangle$ .

Compute: (a)  $\mathbf{F}'(t)$  (b)  $\mathbf{F}''(t)$  (c)  $\mathbf{F}'''(t)$  (d)  $\mathbf{F}^{(13)}(t)$ .

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**EX 10.2.2:** Let  $\mathbf{G}(t) = (\cos t)\hat{\mathbf{i}} - (\sin(5t))\hat{\mathbf{j}} + (\tan t)\hat{\mathbf{k}}$ .

Compute: (a)  $\frac{d\mathbf{G}}{dt}$  (b)  $\frac{d^2\mathbf{G}}{dt^2}$ .

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**EX 10.2.3:** Let  $f(t) = \langle 1, t, t^2 \rangle \cdot [(e^t)\hat{\mathbf{i}} - (t^{-2})\hat{\mathbf{j}} + 3\hat{\mathbf{k}}]$ .

Compute  $f'(t)$ .

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**EX 10.2.4:** Let  $g(\theta) = \|\langle \cos(3\theta), \sqrt{\theta+1}, \sin(3\theta) \rangle\|^2$ .

Compute  $g'(\theta)$ .

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**EX 10.2.5:** Let  $\mathbf{F}(t) = \langle 1, t, t^2 \rangle$  and  $\mathbf{w} = \langle 3, -1, 1 \rangle$ .

Compute: (a)  $\frac{d}{dt} [3t\mathbf{F}(t) + t^2\mathbf{w}]$  (b)  $\frac{d}{dt} [3t\mathbf{F}(t) \cdot t^2\mathbf{w}]$  (c)  $\frac{d}{dt} [3t\mathbf{F}(t) \times t^2\mathbf{w}]$

**EX 10.2.6:** Let  $\mathbf{R}(t) = \langle t^3 - 3t, t^4, 4t^2 \rangle$  be the position vector of a particle in space at time  $t$ .

At  $t = 1$ , find the particle's: (a) velocity (b) acceleration (c) speed (d) direction

(e) When, if ever, is the particle stationary?

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**EX 10.2.7:** Let  $\mathbf{F}(t) = (3t^2)\hat{\mathbf{i}} - \left(\frac{7}{t}\right)\hat{\mathbf{k}}$ . Compute: (a)  $\int \mathbf{F}(t) dt$  (b)  $\int_e^{e^3} \mathbf{F}(t) dt$

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**EX 10.2.8:** Let  $\mathbf{G}(t) = e^t \langle 1, e^{t/2}, t \rangle$ . Compute: (a)  $\int \mathbf{G}(t) dt$  (b)  $\int_0^1 \mathbf{G}(t) dt$

**EX 10.2.9:** Given a particle's velocity  $\mathbf{V}(t) = \langle 1, t, t^2 \rangle$  and initial position  $\mathbf{R}(0) = \langle 1, 2, 3 \rangle$ , find its position vector,  $\mathbf{R}(t)$ .

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**EX 10.2.10:** Given a particle's acceleration  $\mathbf{A}(t) = \langle t, e^t, \sin t \rangle$ , initial velocity  $\mathbf{V}(0) = 3\hat{\mathbf{i}} - 2\hat{\mathbf{j}} + \hat{\mathbf{k}}$ , and initial position  $\mathbf{R}(0) = \langle 1, -2, 2 \rangle$ , find its: (a) velocity vector  $\mathbf{V}(t)$  (b) position vector  $\mathbf{R}(t)$ .

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**EX 10.2.11:** Is  $\mathbf{F}(t) = \langle t^2, \cos t, \sin(t^2) \rangle$  smooth or piecewise smooth over interval  $(-\pi, \pi)$ ? (Justify answer)

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**EX 10.2.12:** Is  $\mathbf{G}(t) = \langle e^t - t, t^{3/2}, \cos(\pi t) \rangle$  smooth or piecewise smooth over interval  $(0, 1)$ ? (Justify answer)