

Vector Functions: **TNB**-Frame & Curvature

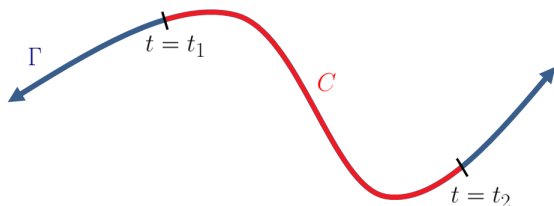
Calculus III

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TTU

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Vector Functions (Arc Length)

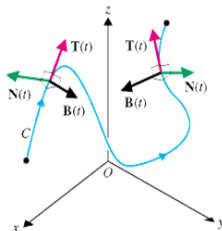
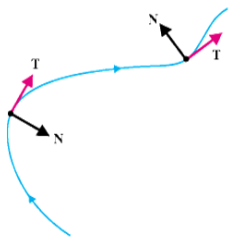


Definition

Let vector function $\mathbf{R}(t) = \langle x(t), y(t), z(t) \rangle$ trace a **piecewise smooth curve** Γ . Let C be the portion of curve Γ that's traced once over the interval $t \in [t_1, t_2]$. Then, the **arc length** of C is defined by:

$$\text{ArcLength}(C) := \int_{t_1}^{t_2} \|\mathbf{R}'(t)\| dt = \int_{t_1}^{t_2} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

TNB-Frame (Definition)



Definition

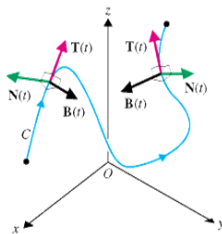
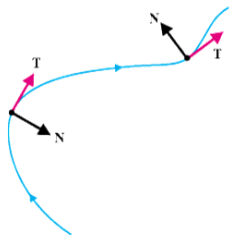
Let vector function $\mathbf{R}(t)$ trace a **smooth curve**. Then:

$$\text{Unit Tangent Vector } \hat{\mathbf{T}}(t) := \frac{\mathbf{R}'(t)}{\|\mathbf{R}'(t)\|} \quad \text{Unit Normal Vector } \hat{\mathbf{N}}(t) := \frac{\hat{\mathbf{T}}'(t)}{\|\hat{\mathbf{T}}'(t)\|}$$

$$\text{Unit Binormal Vector } \hat{\mathbf{B}}(t) := \hat{\mathbf{T}}(t) \times \hat{\mathbf{N}}(t)$$

Collectively, these three vectors form the **TNB-Frame**.

TNB-Frame (Geometric Interpretation)



- The **TNB-Frame** is a **frame of reference**.
- $\hat{T}(t)$ points in the direction of motion along the curve.
- $\hat{N}(t)$ points in the direction the curve is bending.
- $\hat{B}(t)$ is **orthogonal** to both $\hat{T}(t)$ & $\hat{N}(t)$.
- $\hat{N}(t)$ is **orthogonal** to $\hat{T}(t)$.

The claim that $\hat{N}(t) \perp \hat{T}(t)$ is not obvious, so let's prove it....

TNB-Frame (Proof that $\hat{\mathbf{N}}(t) \perp \hat{\mathbf{T}}(t)$)

First, observe that $\hat{\mathbf{T}}(t)$ has norm one.

$$\implies \|\hat{\mathbf{T}}(t)\| = 1$$

$$\implies \|\hat{\mathbf{T}}(t)\|^2 = 1$$

$$\implies \hat{\mathbf{T}}(t) \cdot \hat{\mathbf{T}}(t) = 1 \quad (\mathbf{v} \cdot \mathbf{v} = \|\mathbf{v}\|^2)$$

$$\implies \frac{d}{dt} [\hat{\mathbf{T}}(t) \cdot \hat{\mathbf{T}}(t)] = \frac{d}{dt} [1]$$

$$\implies \hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t) + \hat{\mathbf{T}}(t) \cdot \hat{\mathbf{T}}'(t) = 0$$

$$\implies \hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t) + \hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t) = 0 \quad (\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v})$$

$$\implies 2\hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t) = 0$$

$$\implies \hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t) = 0$$

$$\implies \frac{\hat{\mathbf{T}}'(t) \cdot \hat{\mathbf{T}}(t)}{\|\hat{\mathbf{T}}'(t)\|} = \frac{0}{\|\hat{\mathbf{T}}'(t)\|}$$

$$\implies \frac{\hat{\mathbf{T}}'(t)}{\|\hat{\mathbf{T}}'(t)\|} \cdot \hat{\mathbf{T}}(t) = 0 \quad (c(\mathbf{v} \cdot \mathbf{w}) = (c\mathbf{v}) \cdot \mathbf{w})$$

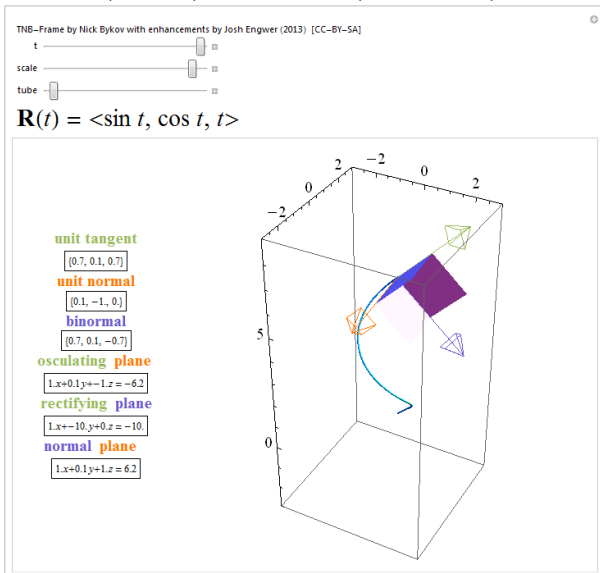
$$\implies \hat{\mathbf{N}}(t) \cdot \hat{\mathbf{T}}(t) = 0$$

$$\implies \hat{\mathbf{N}}(t) \perp \hat{\mathbf{T}}(t)$$

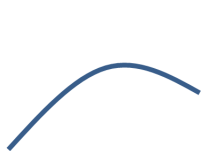
QED

TNB-Frame (DEMO)

(DEMO) TNB-Frame (click below):



Curvature (Definition)



Small Curvature



Large Curvature



Zero Curvature

Definition

Let vector function $\mathbf{R}(t)$ trace a **smooth curve** Γ .
Then, the **curvature** of Γ is defined by:

$$\kappa(t) := \frac{\|\widehat{\mathbf{T}}'(t)\|}{\|\mathbf{R}'(t)\|}$$

where $\widehat{\mathbf{T}}(t)$ is the **unit tangent vector**.

Geometrically, curvature measures the curve's tendency to "bend."

"Curvature's Curse"

CURVE TYPE	PROTOTYPE	CURVATURE FORMULA
3D Vector Function	$\mathbf{R}(t) = \langle x(t), y(t), z(t) \rangle$	$\frac{\ \mathbf{T}'(t)\ }{\ \mathbf{R}'(t)\ }$ OR $\frac{\ \mathbf{R}'(t) \times \mathbf{R}''(t)\ }{\ \mathbf{R}'(t)\ ^3}$
Rectangular Curve	$y = f(x)$	$\frac{ f''(x) }{(1 + [f'(x)]^2)^{3/2}}$
Rectangular Curve	$x = g(y)$	$\frac{ g''(y) }{(1 + [g'(y)]^2)^{3/2}}$
2D Parametric Curve	$\begin{cases} x = f(t) \\ y = g(t) \end{cases}$	$\frac{ x'y'' - y'x'' }{[(x')^2 + (y')^2]^{3/2}}$
Polar Curve	$r = f(\theta)$	$\frac{ r^2 + 2(r')^2 - rr'' }{[r^2 + (r')^2]^{3/2}}$

A Cure for "Curvature's Curse"

CURVE TYPE	PROTOTYPE	CURVATURE FORMULA
3D Vector Function	$\mathbf{R}(t) = \langle x(t), y(t), z(t) \rangle$	$\frac{\ \mathbf{T}'(t)\ }{\ \mathbf{R}'(t)\ ^3}$ OR $\frac{\ \mathbf{R}'(t) \times \mathbf{R}''(t)\ }{\ \mathbf{R}'(t)\ ^3}$
Rectangular Curve	$y = f(x)$	$\frac{ f''(x) }{(1 + [f'(x)]^2)^{3/2}}$
Rectangular Curve	$x = g(y)$	$\frac{ g''(y) }{(1 + [g'(y)]^2)^{3/2}}$
2D Parametric Curve	$\begin{cases} x = f(t) \\ y = g(t) \end{cases}$	$\frac{ x'y'' - y'x'' }{[(x')^2 + (y')^2]^{3/2}}$
Polar Curve	$r = f(\theta)$	$\frac{ r^2 + 2(r')^2 - r r'' }{[r^2 + (r')^2]^{3/2}}$

The Cure: Throw away all these complex formulas for curvature.

A Cure for "Curvature's Curse"

CURVE TYPE	PROTOTYPE	VECTOR ENCAPSULATION
Rectangular Curve	$y = f(x)$	$\mathbf{R}(t) := \langle t, f(t), 0 \rangle$
Rectangular Curve	$x = g(y)$	$\mathbf{R}(t) := \langle g(t), t, 0 \rangle$
2D Parametric Curve	$\begin{cases} x = f(t) \\ y = g(t) \end{cases}$	$\mathbf{R}(t) := \langle f(t), g(t), 0 \rangle$
Polar Curve	$r = f(\theta)$	$\mathbf{R}(t) := \langle f(t) \cos t, f(t) \sin t, 0 \rangle$

The Cure: Convert curve to 3D Vector Function by **vector encapsulation**.

Then use the simplest curvature formula: $\kappa(t) = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{R}'(t)\|}$

Torsion (Definition)



Definition

Let vector function $\mathbf{R}(t)$ trace a **smooth curve** Γ .
Then, the **torsion** of Γ is defined by:

$$\tau(t) := -\hat{\mathbf{N}}(t) \cdot \hat{\mathbf{B}}'(t)$$

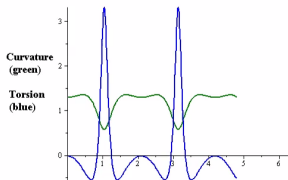
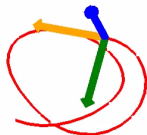
where $\hat{\mathbf{N}}(t)$ is the **unit normal vector** & $\hat{\mathbf{B}}(t)$ is the **unit binormal vector**.

Geometrically, torsion measures the curve's tendency to "twist."

Curvature & Torsion (DEMO)

(DEMO) CURVATURE & TORSION (click below):

Torus knot with tangent vector (brown), normal vector (green) and binormal vector (blue)



Fin

Fin.