A Light-Weight Countermeasure to Forwarding Misbehavior in Wireless Sensor Networks: Design, Analysis, and Evaluation

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Abstract—Due to the lack of centralized coordination, physical protection, and security requirements of inherent network protocols, wireless sensor networks (WSNs) are vulnerable to diverse denial-of-service (DoS) attacks that primarily target service availability by disrupting network routing protocols or interfering with on-going communications. In this paper, we propose a light-weight countermeasure to a selective forwarding attack, called SCAD, where a randomly selected single checkpoint node is deployed to detect the forwarding misbehavior of malicious node. The proposed countermeasure is integrated with timeout and hop-by-hop retransmission techniques to quickly recover unexpected packet losses due to the forwarding misbehavior or bad channel quality. We also present a simple analytical model and its numerical result in terms of false detection rate. We conduct extensive simulation experiments for performance evaluation and comparison with the existing CHEMAS and CAD schemes. The simulation results show that the proposed countermeasure can improve the detection rate and packet delivery ratio (PDR) as well as reduce the energy consumption, false detection rate, and successful drop rate.

Index Terms—Checkpoint-based detection, denial of service (DoS), forwarding misbehavior, selective forwarding attack, wireless sensor networks (WSNs).

I. INTRODUCTION

Wireless sensor networks (WSNs) have been receiving considerable attention as an alternative solution for scalable monitoring and data collection in a hostile or unattended area. A WSN consists of resource-constrained sensor nodes (later nodes) in terms of sensing, computing, or communicating capability. As a part of rapidly emerging Internet of Things (IoT), where a myriad of multiscale nodes and devices are seamlessly blended, WSNs will play an important role in building a ubiquitous computing and communication infrastructure. With the prevalence of cloud, social media, and wearable computing as well as the reduced cost of processing power, storage, and bandwidth, it is envisaged that wirelessly connected smart nodes and devices under IoT will enhance flexible information accessibility and availability as well as change our life further.

Due to the harsh environmental conditions of deployment and the lack of physical protection, however, nodes can be easily captured, tampered, or destroyed by an adversary in WSNs. An open nature of wireless communication can also enable the adversary to overhear, duplicate, corrupt, or alter sensory data. In addition, most conventional network routing protocols are not originally designed to consider the security requirements for malicious attacks. Thus, WSNs are vulnerable to a well-known denial-of-service (DoS) attack that primarily targets service availability by disrupting network routing protocols or interfering with on-going communications.

In this paper, we investigate a selective forwarding attack and propose its countermeasure in multihop WSNs, where single or multiple malicious nodes randomly or strategically drop any incoming packet. The selective forwarding attack primarily targets the network routing vulnerabilities of multihop WSNs by violating an implicit assumption, i.e., all nodes faithfully and collaboratively route packets to a sink. Unlike a blackhole attack [1], where a malicious node blindly drops any incoming packet, it is a nontrivial problem to detect the forwarding misbehavior from temporal node failures or packet collisions. In light of these, we propose a light-weight countermeasure and its corresponding techniques to energy efficiently detect the selective forwarding attack and measure its security resiliency and performance tradeoff through an analytical model and extensive simulation experiments. Our major contribution is briefly summarized in twofold.

1) We propose a single checkpoint-based countermeasure, called SCAD, in WSNs. Unlike prior detection schemes [2]–[6], where multiple checkpoint nodes are deployed, the SCAD deploys a single checkpoint-assisted approach, and its security resiliency and communication performance are measured. The SCAD is also incorporated with timeout and hop-by-hop retransmission techniques to recover unexpected packet losses due to the forwarding misbehavior or bad channel quality.

2) We propose a simple analytical model of the SCAD and show its numerical result in terms of false detection rate. We also revisit prior checkpoint-based and monitor-based detection approaches, CHEMAS [3] and CAD [5], and modify them to work in WSNs for performance comparison.

We develop a customized discrete-event simulation framework using the OMNeT++ [7] and evaluate its performance through extensive simulation experiments in terms of detection rate, successful drop rate, packet delivery ratio (PDR), energy consumption, number of forwarded and overheard packets, and false detection rate. The simulation results indicate that the
proposed countermeasure is a viable detection approach to a selective forwarding attack.

This paper is organized as follows. The prior approaches are summarized and analyzed in Section II. The proposed countermeasure and its simple analytical model are presented in Section III. Section IV is devoted to extensive simulation experiments and performance comparison and analysis. We further explore the potential extensions of proposed countermeasure in Section V. Finally, we conclude the paper in Section VI.

II. Related Work

Both Watchdog and Pathrater approaches [8] are proposed to detect and mitigate routing misbehavior. The Watchdog technique detects a misbehaving node by overhearing its transmission to see whether it correctly forwards a packet. Each node assigns a misbehavior rate to its neighbor nodes and monitors other nodes by updating a table of misbehavior rate in the network. When a source node selects a path for routing, it avoids to include a misbehaving node in the path based on the table. The Watchdog and Pathrater are extended by deploying implicit acknowledgment [9] and overhearing [10] techniques, in which each node monitors the forwarding operations of its neighbor nodes and detects a forwarding misbehavior. In order to seamlessly monitor the forwarding operations, nodes are required to stay in active but it is not feasible especially in a battery-powered network because of energy consumption.

Several acknowledgment-based countermeasures to selective forwarding attacks have been proposed in [2] and its variants [3], [4]. The basic idea is that a set of intermediate nodes located along the forwarding path to a sink acts as a checkpoint node and monitors the forwarding misbehavior by replying an acknowledgment (Ack) packet to a source node. If an intermediate node does not receive the required number of Ack packets, it suspects the next node located in the path as a malicious node and generates an Alarm packet, which is forwarded back to the source node. In [4], Ack packets are forwarded to the sink instead. Since multiple checkpoint nodes generate Ack packets, intermediate nodes may excessively receive and forward Ack packets and consume non-negligible battery energy in resource-constrained WSNs.

In the CAD [5], forwarding misbehaviors are filtered from packet losses due to a bad channel quality or packet collisions based on the observation of channel and network traffic in wireless mesh networks (WMNs). Each node monitors the network traffic of its neighbor nodes and estimates a packet loss rate. A neighbor node is suspected as a malicious node if it shows higher loss rate compared to a detection threshold incorporated with the estimated loss rate. Since the channel quality tends to temporarily fluctuate, it becomes an issue to adaptively set the detection threshold based on time-varying estimated loss rates. The FADE [6] is a variant of the CAD, where each node overhears a link-layer acknowledgment and waits for a two-hop acknowledgment from its downstream nodes after it forwards a packet. This approach still suffers from the number of received and forwarded Ack packets and its energy consumption.

In [11], a DSR-based cooperative bait detection scheme (CBDS) is proposed to detect both selective forwarding and blackhole attacks in mobile ad hoc networks (MANETs). The basic idea is that a source node selects an adjacent node and uses its address as a bait destination address to entice a malicious node to send back a forged or fake route reply (RREP) packet. The malicious node can be detected using a reverse tracing technique.

The HCD [12] is proposed to detect the forwarding misbehaviors of malicious nodes in energy harvesting WSNs. To the best of our knowledge, [12] is the first approach to explore a countermeasure to selective forwarding attack in the realm of energy harvesting WSNs. In the HCD, each node records the trace of forwarding operations through overhearing and exchanges this trace information with its adjacent nodes to detect any forwarding misbehavior. Then each node can reduce the forwarding probability of malicious node to exclude the malicious node from the network. However, the HCD shows high detection latency because of a long window size of trace information exchanged. In [13], a camouflage-based detection scheme, called CAM, is proposed to detect the forwarding misbehavior in energy harvesting motivated networks (EH Nets). The basic idea is that each node hides its current operational status and pretends not to overhear or monitor any on-going forwarding operation of its adjacent nodes to detect a deep lurking malicious node.

In summary, most prior approaches primarily focus on how to increase the detection rate of malicious nodes in the network, where multiple checkpoint nodes are deployed. However, little attention has been paid for a light-weight countermeasure by considering security resiliency and performance tradeoff.

III. Proposed Countermeasure

In this section, we first present both system and adversary models and then propose a light-weight countermeasure to a selective forwarding attack in WSNs, called SCAD. A simple analysis of the SCAD and its numerical result in terms of the false detection rate are also presented.

A. System and Adversary Models

When a node detects an event, it becomes a source node, generates a data packet, and forwards the packet toward a sink in WSNs. To deliver the data packet toward the sink, a simple broadcast-based forwarding [14], directed diffusion [15], or geographic-based routing [16] techniques can be deployed. Each node is aware of its one-hop neighbor nodes by exchanging a one-time single-hop Hello packet piggybacked with its node id [14]. We assume that the network is dense enough to find multiple forwarding candidate nodes. Thus, a single node connecting two subnetworks is not considered because it could be a single point of failure or a malicious node.

A primary goal of the adversary is to attack service availability and degrade the network performance by interfering with on-going communications. An adversary is able to capture and compromise a legitimate node to behave maliciously. A malicious node located along the forwarding path may selectively drop or forward any incoming packet to deafen a sink. The malicious node may also eavesdrop on an on-flying packet and
inject false information or modify its packet header to mislead network traffic. However, if a sender can authenticate a packet with a light-weight digital signature [17], a receiver can easily verify the packet and detect any modification. In this paper, we primarily focus on the selective forwarding attacks or the adversarial scenarios [2]–[6] that cannot be detected by digital signatures and cryptographic primitives.

### B. Single Checkpoint-Based Detection

The SCAD deploys a single checkpoint-assisted approach and consists of three major operations: single checkpoint node selection, timeout, and retransmission. First, when a source node generates a data packet, it randomly selects one of the intermediate nodes located along the forwarding path to a sink as a checkpoint node and piggybacks a random number into the packet. Since the source node independently and randomly selects a checkpoint node per-packet basis, it is not trivial for an adversary to predict the checkpoint node for the next data packet. Here, we do not consider dynamically changing routing paths for the same packet during the transmission, because it can exclude the checkpoint node selected by the source node in the path. When a node receives the data packet, it caches the packet in its local storage and checks whether it is selected as a checkpoint node by comparing its one-way hash and map functions [3]. If both functions are equal to one (e.g., selected as a checkpoint node by comparing its one-way hash and map function), the node forwards the packet to the next node and replies an Ack packet back to the source node. In the SCAD, we propose a timeout technique to reduce unnecessary packet delivery latency, which can be caused by unexpected packet loss due to the forwarding misbehavior or bad channel quality. We define a timeout technique as a tuple, \([T^C, T^S]\), where \(T^C\) and \(T^S\) are timeout periods of an Ack packet originated from a checkpoint node (C) and the sink (S), respectively. If a node is located in \(G_{down}\), its \(T^C\) is zero. In order to estimate the timeout period, we consider a single-hop based estimated trip time \((T_{ETT})\) that can be measured from when a node forwards a data packet \((T_{F,data})\) to when it receives an Ack packet either from the checkpoint node or the sink \((T_{R,Ack})\). Then \(T_{ETT}\) is divided by \(H_k\), which is the number of hops counted from the node to the check- node and the sink when a node forwards a data packet with sequence number \(k\). \(T_{ETT}\) is updated by the low-pass filter with a filter gain constant \(\alpha\)

\[
T^d_{ETT} = \alpha \cdot T^d_{ETT} + (1 - \alpha) \cdot T_{ETT,k-1} - H_k \cdot \delta
\]

Thus, the timeout period is expressed as

\[
T^d = T^d_{ETT} \cdot H_k + H_k \cdot \delta
\]
Ack or Alarm packet again, it forwards another Alarm packet again, quits the retransmission, and discards the cached data packet. For example, suppose $n_8$ drops a data packet forwarded from $n_7$ in Fig. 1. Then $n_7$ generates an Alarm packet and retransmits its cached data packet to $n_8$. If $n_8$ drops the retransmitted data packet again, $n_7$ generates another Alarm packet. The more malicious nodes drop retransmitted data packets, the sooner the source node detects their forwarding misbehaviors.

Note that the source node may isolate a suspected node from the network after receiving a number of Alarm packets by broadcasting a packet piggybacked with the id of suspected node, or reducing a forwarding probability of the suspected node [12]. However, this is out of the scope of this paper. Major operations of the proposed countermeasure are summarized in Fig. 3.

C. Analysis of the Proposed Countermeasure

In this paper, we analyze the SCAD in terms of average false detection rate. When a packet (e.g., data, Ack, or Alarm) is lost because of the bad channel quality, however, a node may mistakenly prosecute the next located legitimate node as a malicious node, resulting in the false detection. In Fig. 1, e.g., $n_5$ drops a data packet forwarded from $n_4$. Then, $n_4$ generates an Alarm packet to prosecute the forwarding misbehavior of $n_5$ when its timer expires, and forwards the Alarm packet back to the source node. Due to the bad channel quality, the Alarm packet can be lost again during the transmission from $n_5$ to $n_4$. Then $n_4$ generates another Alarm packet to prosecute the forwarding misbehavior of $n_5$ when its timer expires, resulting in a false detection. In this analysis, we assume that the bad channel quality in terms of channel error primarily causes packet loss without considering packet drop conducted by malicious nodes to clearly see the impact on the false detection.

Suppose total $N$ nodes excluding the sink and source node are located in the forwarding path, where $m$ (≥1) of them are malicious nodes. $\varphi$ is a channel error rate, either 10% or 20%. Let $P_F$ be an average false detection rate, which is the sum of average false detection rates of data ($P_{FD}$), Ack ($P_{FA}$), and Alarm ($P_{FM}$) packet losses. Then $P_F$ is expressed as

$$P_F = P_{FD} + P_{FA} + P_{FM}. \quad (4)$$

First, $P_{FD}$ is expressed as

$$P_{FD} = \frac{1}{n - m - 1}(P_{FD1} + P_{FD2}) \quad (5)$$

where

$$P_{FD1} = \sum_{i=1}^{m} \sum_{j=0}^{h_i-1} (1 - \varphi)^{2j+2h_i-1} \varphi \quad (6)$$

$$P_{FD2} = \sum_{j=0}^{n-h_0-2} (1 - \varphi)^{2j+2h_0} \varphi. \quad (7)$$

Here, $h_i$ ($0 \leq i \leq m$, and $h_0 = 0$) is the number of hops from the $i$th malicious node to the first node (e.g., $n_1$). $P_{FD}$ is the average false detection rate of data packet loss between the first and the last nodes (e.g., $n_1$ to $n_{10}$ in Fig. 1). In (6), $P_{FD1}$ is the total false detection rates between the first node and the last malicious node (e.g., $n_1$ to $n_8$). Note that a data packet loss can lead to both false and correct detection cases. In a false detection case based on Fig. 1, if a data packet is lost during the transmission from $n_3$ to $n_4$, a malicious node $n_3$ generates an Alarm packet to prosecute the forwarding misbehavior of a normal node $n_4$. If this Alarm packet is forwarded to the source node, a false detection can occur. In case of a correct detection, however, suppose a data packet is lost during the transmission from $n_2$ to $n_3$. Then a legitimate node $n_2$ generates an Alarm packet to prosecute a malicious node $n_3$, which can lead to a correct detection. In (7), $P_{FD2}$ is the total false detection rates...
between the last malicious node and the last node on the forwarding path (e.g., \( n_k \) to \( n_{10} \)). Unlike to \( P_{FA1} \), only a false detection can occur because there is no malicious node between \( n_k \) to \( n_{10} \).

Second, \( P_{FA} \) is expressed as

\[
P_{FA} = P_{FA1} + P_{FA2}
\]

(8)

\[
P_{FA1} = \frac{RD_{chk}}{h_{chk} - k} (P_{FA1, 1} + P_{FA1, 2})
\]

(9)

where

\[
RD_{chk} = (1 - \varphi)^{h_{chk}}
\]

(10)

\[
P_{FA1, 1} = \sum_{j=0}^{h_{chk} - h_k - 1} (1 - \varphi)^{h_{chk} - 1} \varphi
\]

(11)

\[
P_{FA1, 2} = \sum_{i=k}^{1} \sum_{j=0}^{h_i - h_{i-1} - 2} (1 - \varphi)^{h_{i-1} - 1} \varphi.
\]

(12)

Also

\[
P_{FA2} = \frac{RD_{sink}}{n - m - 1} (P_{FA2, 1} + P_{FA2, 2})
\]

(13)

where

\[
RD_{sink} = (1 - \varphi)^{n-1}
\]

(14)

\[
P_{FA2, 1} = \sum_{i=0}^{n-m-2} (1 - \varphi)^{n-2} \varphi
\]

(15)

\[
P_{FA2, 2} = \sum_{i=m}^{1} \sum_{j=0}^{h_i - h_{i-1} - 2} (1 - \varphi)^{h_{i-1} - 1} \varphi.
\]

(16)

Here, \( h_{chk} \) is the number of hops from the checkpoint node to the first node (e.g., \( n_5 \) to \( n_1 \), \( h_{chk} = 4 \)), \( k \) is the number of malicious nodes located in \( G_{UP} \). \( P_{FA1, 2} \) becomes zero when \( k = 0 \).

In (8), \( P_{FA} \) is an average false detection rate of the first and second \( Ack \) packet losses from the checkpoint node or the sink to the first node (e.g., \( n_5 \) to \( n_1 \) or sink to \( n_1 \)), respectively. \( RD_{chk} \) and \( RD_{sink} \) are the probabilities that a data packet reaches to the checkpoint node and the sink in (10) and (14), respectively. In (9), \( P_{FA1} \) is an average false detection rate of the first \( Ack \) packet loss during the transmission between the checkpoint node and the first node (e.g., \( n_5 \) to \( n_1 \)).

In (11), \( P_{FA1, 1} \) is the total false detection rates between checkpoint node and the first malicious node (e.g., \( n_5 \) to \( n_3 \)). Similar to data packet loss, an \( Ack \) packet loss can lead to both false and correct detections. For example, an \( Ack \) packet loss during the transmission from \( n_4 \) to \( n_3 \) can lead to a false detection because a malicious node \( n_3 \) generates an \( Alarm \) packet to prosecute the forwarding misbehavior of a normal node \( n_4 \). If an \( Ack \) packet is lost during the transmission from \( n_4 \) to \( n_3 \), a correct detection can occur because a normal node \( n_2 \) generates an \( Alarm \) packet to prosecute the malicious node \( n_3 \). In (12), \( P_{FA1, 2} \) is the total false detection rates between the first malicious node and the first node on the forwarding path (e.g., \( n_3 \) to \( n_1 \)). Since no malicious node exists between \( n_3 \) and \( n_1 \), only a false detection can occur.

In (13), \( P_{FA2} \) is an average false detection rate of the second \( Ack \) packet loss during the transmission between the sink and the first node (e.g., sink to \( n_1 \)). Similar to the first \( Ack \) packet loss, both false and correct detections of \( Ack \) packet loss can occur during the transmission between the sink and the first malicious node. Thus, only a false detection can occur during the transmission between the first malicious node and the first node. In (15) and (16), \( P_{FA2, 1} \) is the total false detection rates between the sink and the first malicious node (e.g., sink to \( n_3 \)), while \( P_{FA2, 2} \) is the total false detection rates between the first malicious node and the first node in the forwarding path (e.g., \( n_3 \) to \( n_1 \)).

Third, \( P_{FM} \) is expressed as

\[
P_{FM} = \frac{1}{n - m - 1} (P_{FM1} - P_{FM2})
\]

(17)

where

\[
P_{FM1} = \sum_{i=1}^{n-2} (1 - \varphi)^{2i-1} \varphi^2
\]

(18)

\[
P_{FM2} = \sum_{i=1}^{m} (1 - \varphi)^{2h_i - 1} \varphi^2.
\]

(19)

\( P_{FM} \) is an average false detection rate of \( Alarm \) packet loss between the first and the last nodes. In (18), \( P_{FM1} \) includes the probabilities of both false and correct detections for \( Alarm \) packet loss, respectively. In case of a false detection based on Fig. 1, suppose \( n_6 \) intentionally drops a data packet and \( n_5 \) generates an \( Alarm \) packet to prosecute the forwarding misbehavior of \( n_6 \). If the \( Alarm \) packet is lost during the transmission from \( n_5 \) to \( n_4 \), \( n_4 \) generates another \( Alarm \) packet to prosecute the forwarding misbehavior of \( n_5 \). If this \( Alarm \) packet is forwarded to the source node, then a false detection can occur. In case of a correct detection, denoted as \( P_{FM2} \) in (19), suppose a data packet is lost during the transmission from \( n_3 \) to \( n_4 \), \( n_3 \) generates an \( Alarm \) packet to prosecute the forwarding misbehavior of \( n_4 \), and this \( Alarm \) packet is lost during the transmission from \( n_3 \) to \( n_2 \). Then \( n_2 \) generates another \( Alarm \) packet to prosecute the forwarding misbehavior of \( n_3 \), leading to a correct detection.

In Fig. 4, we show a numerical result of the impact of number of malicious nodes (\( m \)) and channel error rate (\( \varphi \)) on the average false detection rate based on the aforementioned analyses. Here, 20 intermediate nodes are located in the forwarding path.
path, where one to six malicious nodes are randomly located. As the $m$ increases, overall $P_F$ decreases with different $\phi$ in Fig. 4(a) and (b). In particular, higher $\phi$ leads to higher $P_{FD}$ in Fig. 4(b). The more data packets are lost, the harder nodes detect whether the packets are lost or dropped. As the $m$ increases, $P_{FD}$ decreases because data packet has higher probability of being dropped by malicious nodes than that of being lost during the transmission. In $P_{FA}$, malicious nodes are reluctant to drop any $Ack$ packet because this forwarding misbehavior may enforce nodes to generate a series of $Alarm$ packets. In Fig. 4(b), lower $P_{FA}$ is observed with $\phi = 20\%$ compared to $10\%$ channel error rate in Fig. 4(a). This is because more data packets are lost during the transmission and thus, the number of Ack packets reduces and the $m$ does not affect $P_{FA}$ much. Both $m$ and $\phi$ affect $P_{FM}$. Higher $\phi$ leads to higher $P_{FM}$ in Fig. 4(b). As the $m$ increases, $P_{FM}$ slightly increases because $\frac{1}{n-m-1}$ increases in $P_{FM}$.

IV. PERFORMANCE EVALUATION

A. Simulation Testbed

We conduct extensive simulation experiments using the OMNeT++ [7] for performance evaluation and analysis. A $300 \times 300$ (m$^2$) rectangular network area is considered, where 250 nodes are uniformly distributed. The communication range of each node is 12.3 (m). The radio model simulates CC2420 with a normal data rate of 250 Kbps [18]. The channel error rate is randomly changed from 0% to 10% with a step size 2%. During the simulation. A packet injection rate is 0.5 packet/s and each packet size is 1 KByte. One to six malicious nodes are randomly located along the forwarding path between a source and the sink. A set of malicious nodes selectively drops any incoming packet with a packet drop rate, either 10% or 20%. The simulation parameters are summarized in Table 1.

In this paper, we measure the performance in terms of detection rate, successful drop rate, PDR, energy consumption, number of forwarded and overheard packets, and false detection rate by changing key simulation parameters, including number of malicious nodes, packet drop rate, and channel error rate. For performance comparison, we denote the proposed countermeasure without or with retransmission as SCAD or SCAD-rt, respectively. They are compared with the CHEMAS [3] that is configured with two or three segments ($k$), denoted as CHE-k2 or CHE-k3, respectively, where an $Ack$ packet traverses $k$ segments before being dropped by a checkpoint node.

The proposed countermeasure is also compared with the CAD [5], where the detection threshold values are set between 0.08 and 0.15.

B. Performance Comparison

In Fig. 5, as the number of malicious nodes ($m$) increases, the detection rate decreases in both CHE-k2 and CHE-k3. The probability of multiple malicious nodes being selected as a checkpoint node increases, and they may not report the forwarding misbehavior witnessed from adjacent nodes to the source. The lower detection rate is observed with the smaller $k$. Since $Ack$ packet traverses the less number of hops along the forwarding path, each intermediate node receives less number of $Ack$ packets forwarded from the downstream. The CAD is sensitive to the detection threshold value and shows about 95% and 50% detection rates in low (0.08) and high (0.15) threshold values, respectively. Due to the temporarily fluctuating channel quality, it becomes an issue to adaptively set the detection threshold value based on the time-varying estimated loss rates. Thus, the detection rate highly depends on the detection threshold value. Unlike to the CAD, both SCAD and SCAD-rt show high and stable detection rates for entire $m$. Since a single checkpoint node is selected and replies an $ Ack$ packet, more intermediate nodes are supposed to receive and forward the $Ack$ packet to the source. If an upstream legitimate node does not receive an $Ack$ packet before its timeout period, it generates an $Alarm$ packet to prosecute the next node for forwarding misbehavior.

In Fig. 6, both successful drop rate and PDR are measured by varying the $m$ and packet drop rate. In Fig. 6(a), the $m$ significantly affects the successful drop rate in both CHE-k2 and CHE-k3. The CHE-k2 shows higher successful drop rate than that of the CHE-k3. This is because an $Ack$ packet travels less number of hops and each intermediate node receives less number of $Ack$ packets compared to that of the CHE-k3. Multiple malicious checkpoint nodes can cooperate each other and drop data packets without being detected. Depending on the $k$, the CHEMAS has a performance tradeoff between security resilience and communication overhead. Note that the SCAD, SCAD-rt, and CAD show zero successful drop rate. In Fig. 6(b), under 10% packet drop rate, PDR quickly decreases as the $m$ increases because more data packets are randomly dropped by malicious nodes. The SCAD, SCAD-rt, and CAD show higher PDR than that of the CHE-k2 and CHE-k3 for entire $m$ because the collusion of multiple malicious nodes selected

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network area</td>
<td>$300 \times 300$ m$^2$</td>
</tr>
<tr>
<td>Number of nodes</td>
<td>250</td>
</tr>
<tr>
<td>Number of malicious nodes</td>
<td>1–6</td>
</tr>
<tr>
<td>Channel error rate</td>
<td>0–10%</td>
</tr>
<tr>
<td>Radio data rate</td>
<td>250 Kbps</td>
</tr>
<tr>
<td>Packet injection rate</td>
<td>0.5 packet/s</td>
</tr>
<tr>
<td>Packet size</td>
<td>1 KByte</td>
</tr>
<tr>
<td>Packet drop rate</td>
<td>10% or 20%</td>
</tr>
<tr>
<td>Radio range</td>
<td>12.3 m</td>
</tr>
<tr>
<td>Radio model</td>
<td>CC2420</td>
</tr>
<tr>
<td>Simulation time</td>
<td>1000 s</td>
</tr>
</tbody>
</table>

![Fig. 5. Detection rate against the number of malicious nodes (10% packet drop rate).](image-url)
as a checkpoint node does not affect to the SCAD, SCAD-rt, and CAD. The SCAD-rt shows the best performance (about 90% or more) because each intermediate node can quickly retransmit its cached data packet to the next node if the data packet is dropped or lost. In Fig. 6(c), overall PDRs decrease with a larger packet drop rate 20%. However, the SCAD-rt still shows the best performance and the PDR decreases gracefully compared to that of the CHE-k2, CHE-k3, and CAD.

In Fig. 7, the energy consumption is measured based on the number of forwarded and overheard packets [19] by varying the $m$ and packet drop rates. In Fig. 7(a), both SCAD and SCAD-rt show lower energy consumption than that of the CHE-k2 and CHE-k3 because of less number of Ack packets traversed along the forwarding path. Since an Ack packet traverses three and two segments before being dropped by a checkpoint node in the CHE-k3 and CHE-k2, respectively, the CHE-k3 consumes more energy than that of the CHE-k2. The SCAD-rt also consumes more energy than that of the SCAD to retransmit lost or dropped data packets. In Fig. 7(b), overall energy consumptions decrease with higher packet drop rate (20%) because more data packets are dropped by malicious nodes. Note that we measure the number of forwarded and overheard packets in Fig. 8(a) and (b), respectively. The CHE-k2, CHE-k3, and SCAD-rt send Ack packets for detecting forwarding misbehaviors, but the CAD implicitly monitors the network traffic. Thus, intermediate nodes in the CHE-k2, CHE-k3, and SCAD forward more packets but ultimately the CAD overhears more packets, because each node always needs to wake up and observe any on-going packet.

In Fig. 9, we measure the false detection rates by varying the $m$ and channel error rates ($e$). In Fig. 9(a), both SCAD and SCAD-rt show the lowest false detection rate because the number of Ack packets generated by a single checkpoint node reduces. Note that this false detection rate is lower than that of the aforementioned analysis (see Fig. 4). Since the analysis extensively counts all packet losses due to the bad channel quality, it shows an upper bound of false detection rate. Multiple checkpoint nodes generate Ack packets and each intermediate node frequently forwards them to the source in the CHE-k2 and CHE-k3. Thus, more Ack packets can be lost due to the bad channel quality, resulting in higher false detection rate. The CAD with higher detection threshold value (i.e., 0.15) shows the highest false detection rate, because more intermediate nodes mistakenly consider a packet loss as a forwarding misbehavior. In Fig. 9(b), as the $e$ increases, overall false detection rates increase because it becomes harder to detect the forwarding misbehavior of malicious nodes from packet loss due to the bad channel quality.
In this section, we first investigate the SCAD of its applicability to other attacks and then further explore its design issues and extensions for future research.

A. Immunity to Other Attacks

We investigate the SCAD whether it can be applied to two well-known attacks: colluding collision attack and power control attack [21].

1) Colluding Collision Attack: A multiple number of malicious nodes may collude together and create a collision at the next hop on purpose by simultaneously sending packets. The IEEE 802.11 medium access control (MAC) protocol with request-to-send (RTS)/clear-to-send (CTS) exchange can be deployed to reduce packet collisions. However, the 802.11 MAC with RTS/CTS exchange is often disabled in many WSN applications because of its non-negligible energy consumption [21]. Thus, it is not trivial to avoid colluding collision attack, but this attack can be detected by the SCAD. In Fig. 1, suppose \(n_6\) sends a data packet to \(n_7\) and its colluding \(n_8\) also simultaneously send any packet to \(n_7\). Then \(n_7\) fails to receive the data packet due to the collision. In the SCAD, since the data packet is lost, the sink will not reply an Ack packet back to the source node. Thus, \(n_5\) cannot receive the Ack packet from the sink before its timer expires, and it will generate an Alarm packet to prosecute the forwarding misbehavior of \(n_6\) and forward the Alarm packet back to the source node.

2) Power Control Attack: A malicious node may control its transmission power and forward a packet to exclude a legitimate node from its communication range. This power control attack is similar to selective forwarding attack, and it can be detected by the SCAD. In Fig. 1, suppose \(n_2\) forwards a data packet to \(n_3\) and the data packet is relayed to \(n_4\). Then \(n_2\) sets two timers for the Ack packets originated from the sink and \(n_5\), respectively. If \(n_3\) reduces its transmission power and forwards the data packet, \(n_4\) fails to receive the data packet. In the SCAD, since \(n_5\) cannot receive the data packet, it will not reply the Ack packet back to the source node. Thus, \(n_2\) cannot receive the Ack packet from the checkpoint node before its timer expires, and it will generate an Alarm packet to prosecute the forwarding misbehavior of \(n_3\) and forward the Alarm packet back to the source node.

B. Potential Enhancements

We explore design issues and extensions to see the full potential of our approach for efficiently mitigating the forwarding misbehavior.

1) Alternative Path for Retransmission: In the SCAD, if a node does not receive an Ack or Alarm packet before its timer expires, due to the forwarding misbehavior or bad channel quality, it generates an Alarm packet to prosecute the next node for its forwarding misbehavior. Then the node retransmits its cached data packet to the same next node based on the proposed hop-by-hop retransmission. If the next node drops the retransmitted data packet again, the source node will choose an alternative forwarding path without including this suspected node. Thus, we plan to deploy a bypass technique [22], [23] in the hop-by-hop retransmission by selecting an alternative forwarding path from the node that executes the next node and generates an Alarm packet. This approach can avoid transmitting the cached data packet to the same suspected node over and over until the source node changes the path. For example, when a node detects the forwarding misbehavior of the next node, it selects another one-hop node as a forwarding node and transmits the cached data packet. However, an alternative path may exclude the checkpoint node already selected from the source node during the transmission. Then the node that generates an Alarm packet randomly chooses a checkpoint node, piggybacks the id of checkpoint node into the cached data packet, and forwards the data packet towards the sink. Note that when a malicious node selects an alternative path, it may chooses a path which is far longer than the shortest or optimal path to intentionally increase the packet delivery latency, called vampire attack [24].

2) Active Detection: In the SCAD, a single checkpoint node generates an Ack packet and each intermediate node located along the forwarding path passively monitors any forwarding behavior of its next node. Similar passive monitoring-based approaches are also found in [5], [8]–[10], and [12]. Since the detection rate highly depends on how frequently malicious nodes conduct the forwarding misbehavior, it can be significantly reduced if multiple malicious nodes collude together. Thus, we consider a camouflage-based detection [13], in which each node pretends not to overhear on-going communication.
but monitors the forwarding behavior of its adjacent nodes to
detect a deep lurking malicious node. We plan to extend the
SCAD by deploying an active detection approach, where each
intermediate node hides its operational status (i.e., a checkpoint
node), counts the number of forwarding misbehaviors, and
selects the next forwarding node. A suspected node recorded
with a high number of forwarding misbehaviors will not be
chosen very often as a forwarding node.

In summary, we compare the proposed countermeasure with
prior approaches and summarize their detection strategies in
terms of six criteria in Table II.

VI. CONCLUDING REMARKS

In this paper, we proposed a light-weight countermeasure,
called SCAD, to mitigate the forwarding misbehavior in WSNs.
In the SCAD, a single checkpoint-assisted approach incorpo-
rated with timeout and retransmission techniques can efficiently
improve the detection rate as well as reduce the energy con-
sumption, false detection rate, and successful drop rate. The
SCAD can achieve more than 90% PDR with less energy con-
sumption compared to prior CHEMAS and CAD schemes. A
simple analytical model of the SCAD and its numerical result
in terms of false detection rate are also presented. To see the full
potential of our approach, we discuss the design issues and pos-
sible extensions of the SCAD. The numerical and simulation
results indicate that the proposed countermeasure is a viable
approach in WSNs.

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